

PROJECT PLACIS: MINIBEE

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DESIGN OF THE PROJECT

The development process of lightweight subsonic aircraft can be broke down on the following procedures:

- Specification and requirements
- Initial Study
- Initial Project
- Project
- Manufacturing
- Ground Tests
- Flight Tests

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Initial Study

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Manufacturing

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Development timeline

These procedures were proposed by BARROS, and compose a synthesis of the four main methodologies on the aeronautic field: The works of TORENBECK, RAYMER, ROSKAN and VANDAELE

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Specification and
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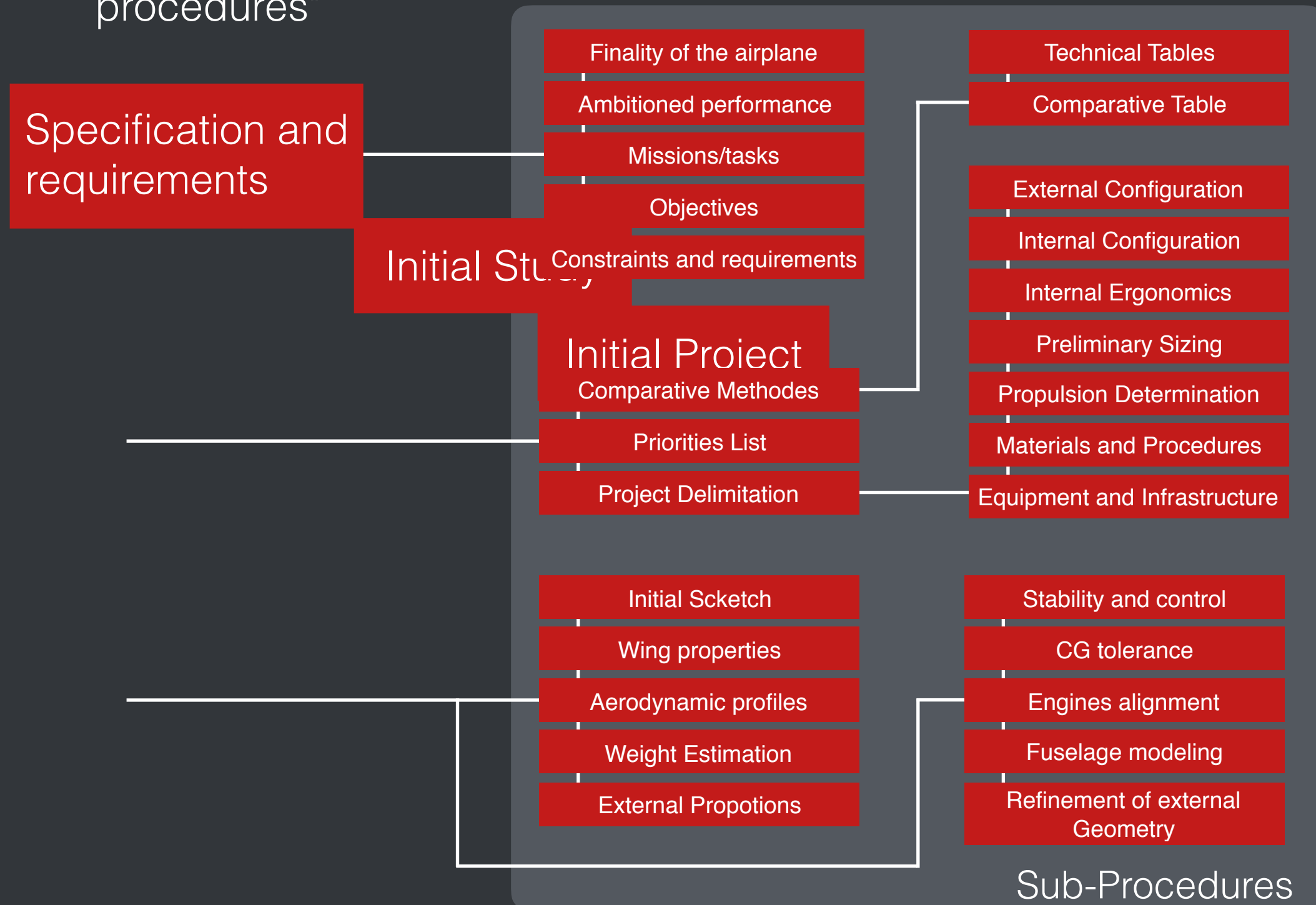
Development timeline



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DESIGN OF THE PROJECT

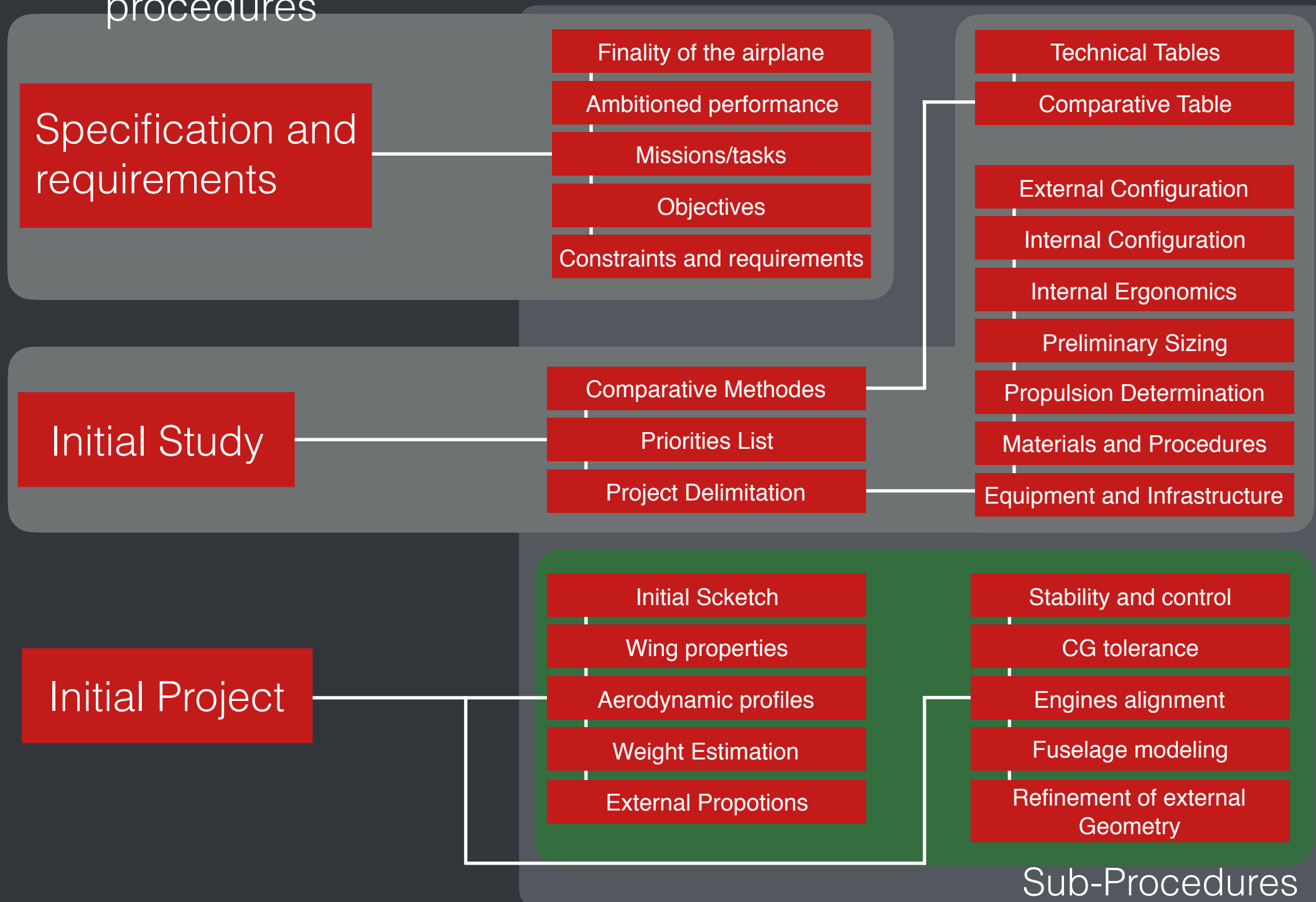
Each of these procedures can be broke down in so called "Sub-procedures"



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PROJECT MANAGEMENT

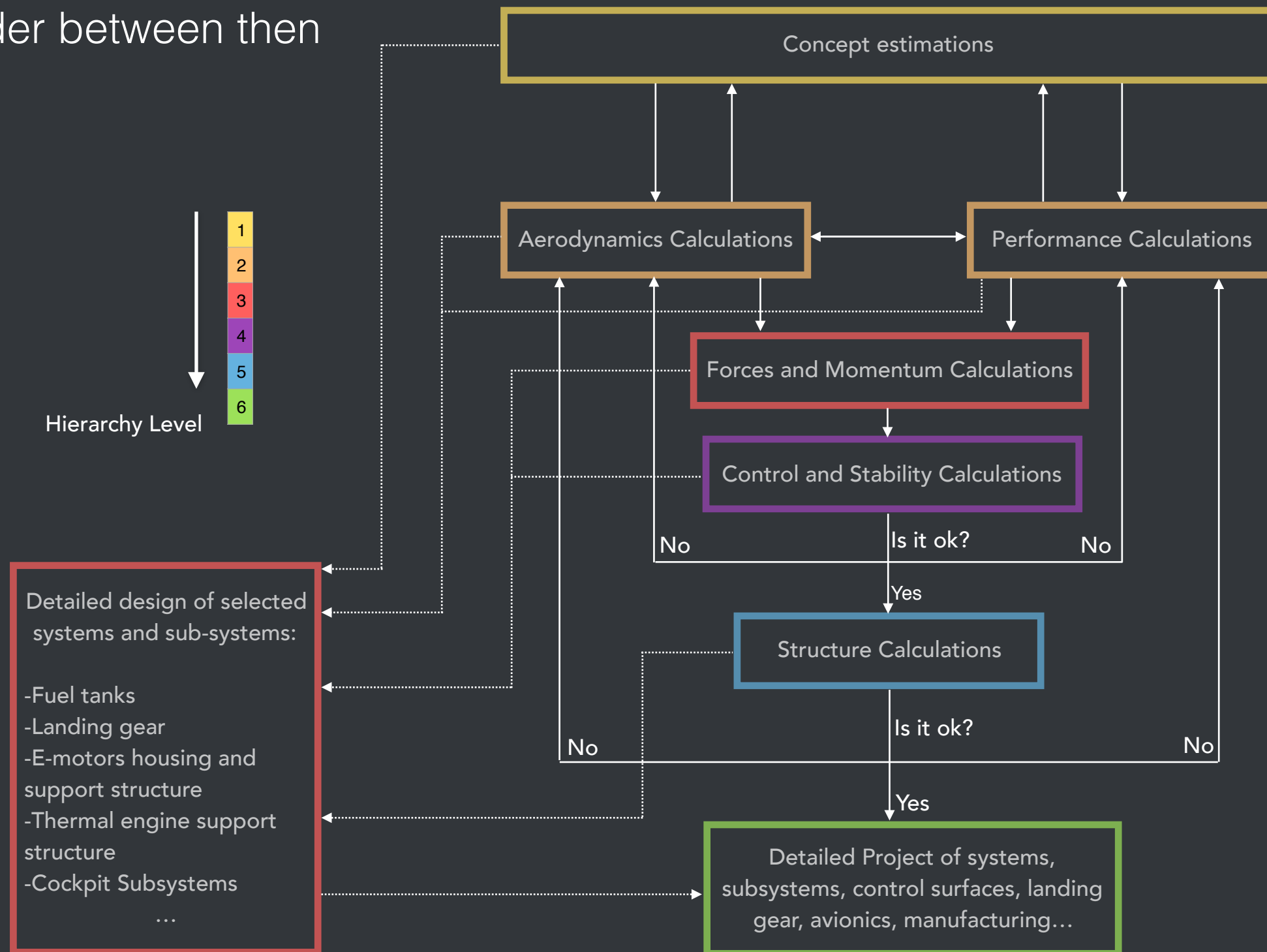
1. Identify the main project areas, relate them, and set a hierarchy order between them
2. List the inputs and outputs of each of those areas to define the tasks that must be done
3. Relate 1 and 2 in a time board and divide the tasks between universities

PROJECT MANAGEMENT

1. Identify the main project areas, relate them, and set a hierarchy order between them
 - Concept Estimations
 - Aerodynamic Calculations
2. List the inputs and outputs of each of those areas to define the tasks that must be done
 - Performance Calculations
 - Force and Moment Calculations
 - Structure Calculations
 - Detailed project of Systems and subsystems
3. Relate 1 and 2 in a time board and divide the tasks between universities

PROJECT MANAGEMENT

1. Identify the main project areas, relate them, and set a hierarchy order between them

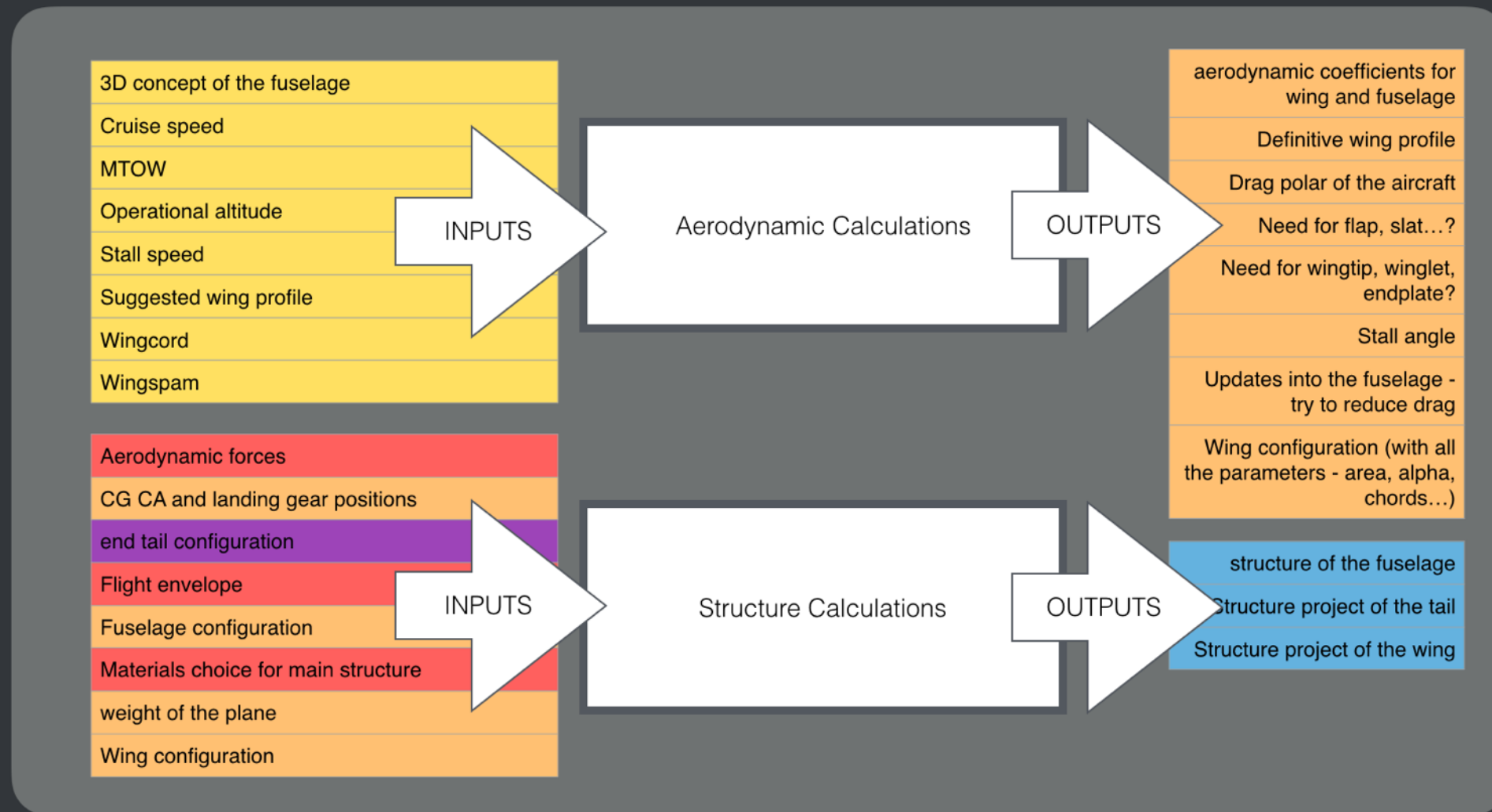


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PROJECT MANAGEMENT

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■ ■ ■

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PROJECT MANAGEMENT

1. Identify the main project areas, relate then, and set a hierarchy order between then

2. List the inputs and outputs of each of those areas to define the tasks that must be done

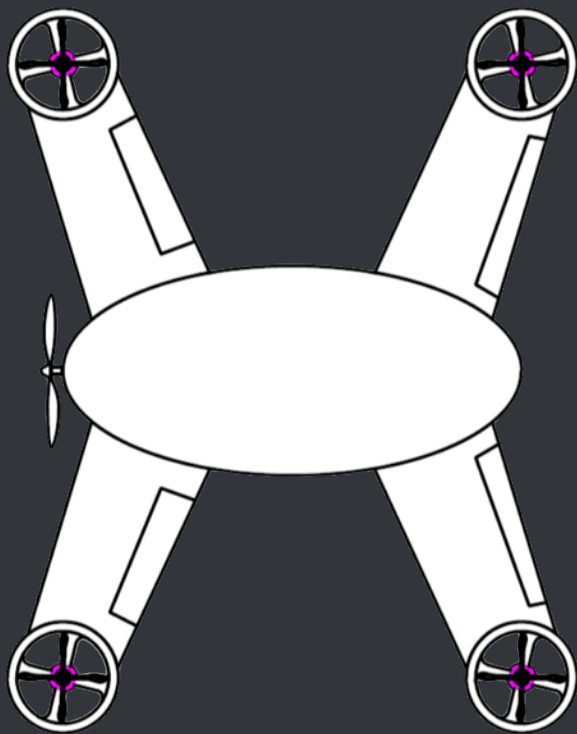
Tasks/Deadline	Completed? (/X/)	11/Dec/2015	18/Dec/2015	25/Dec/2015	1/Jan/2016	8/Jan/2016	15/Jan/2016	22/Jan/2016	29/Jan/2016	5/Feb/2016
3D concept of the fuselage										
Autonomy										
Batteries estimation										
CG approximate position and allowed movement		Supméca	Supméca							
CG position		Supméca	Supméca							
Choice of engines										
Client requirements										
Cruise speed										
Early calculations and estimations										
Empty weight										
Existing products										
General dimensions										
Ideas of the team										
Law regulations										
Literature guidelines and references										
Motor characteristics										
Motor geometry and size										
MTOW										
Number of passengers										
Operational Altitude										
Pilot visibility requirements		Estaca	Estaca							
possible comercial aplicatoinis										
Propeller size and characteristics										
Proposed engines										
Sketch architecture										
Sketch geometry										
Stall speed		Supméca	Supméca							
Suggested propellers		Supméca	Supméca							
Suggested wing profile										
Supplied power										
Wing cord										
Wingspan										
aerodynamic coefficients for wing and fuselage		Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca
Allowed geometry and contours for the fuel tank										
CG and CA positions		Supméca	Supméca	Supméca	Supméca	Supméca				
Critical landing forces		Supméca								
curves like power vs speed, required power vs. available power...							Central	Central	Central	
Definitive batteries		Estaca	Estaca							
Definitive engine location		Estaca	Estaca							
Definitive propellers		Estaca	Estaca							
Definitive wing profile										
Drag polar of the aircraft		Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca
Fuel consumption		Polito								

Fuselage configuration	Supméca	Supméca								Supméca
Geometry of the plane		Estaca								
Landing gear position										
Major systems and subsystems position	Polito									
Material choice for the fuselage	Estaca									
Maximum speed			Central	Central	Central					
Minimum speed			Central	Central	Central					
e-Motor location	Estaca									
Need for flap, slat...?						Supméca	Supméca			
Need for wingtip, winglet, endplate?	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca			
Position of the thermic engine	Estaca									
Rate of ascent	Central	Central								
Required power	Central	Central								
Stall angle						Supméca	Supméca			
Static stability parameters	Estaca									
take off speed			Central	Central	Central	Central				
Updates into the fuselage - try to reduce drag						Supméca	Supméca	Supméca		
Velocity of the plane			Central	Central	Central					
Weight of the plane	Supméca	Supméca								
Wing configuration	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca
Wing configuration (with all the parameters - area, alpha, chords...)	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca
Wing dimensions	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca	Supméca
Aerodynamic forces										
Cockpit internal geometry			Estaca	Estaca	Estaca					
Detailed project of e motor housing	Supméca					Supméca	Supméca	Supméca	Supméca	Supméca
detailed project of fuel tank			Polito	Polito	Polito	Polito				
Detailed project of landing gear		Supméca	Supméca	Supméca	Supméca					
Flight envelope								Central	Central	Central
Forces and momentums needed for control and stability								Central	Central	Central
Forces and momentums needed for the structures calculations										
Fuel tank geometry and location		Polito								
Fuel tank weight			Polito	Polito	Polito	Polito				
e-Housing and structures geometry	Supméca									
Landing gear geometry		Supméca	Supméca	Supméca	Supméca					
Materials choice for main structure								Estaca	Estaca	Estaca
passenger disposition on cockpit			Estaca	Estaca	Estaca					
Structure requirements of cockpit								Estaca	Estaca	Estaca
Command surfaces configuration and dimensions										
Dimension and position of end tail										
end tail configuration										
structure of the fuselage										
Structure project of the tail										
Structure project of the wing										

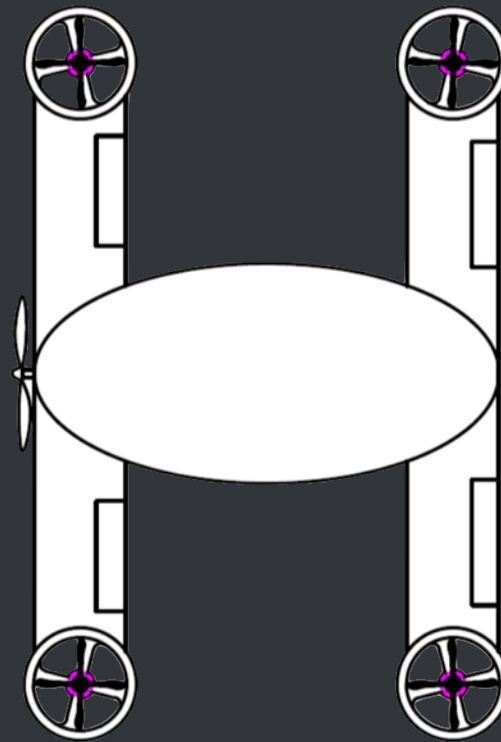
3. Relate 1 and 2 in a time board and divide the tasks between universities

AIRCRAFT CONFIGURATION

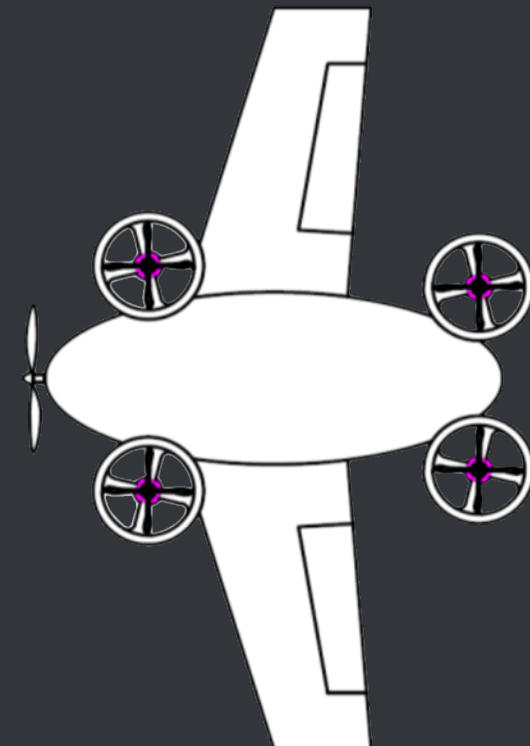
The first dilemma of MiniBee:



X



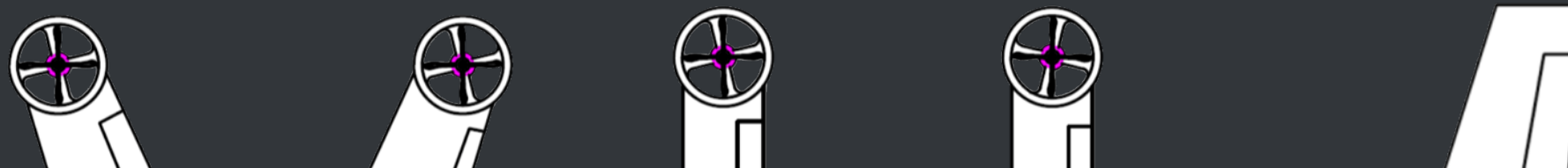
H



A

AIRCRAFT CONFIGURATION

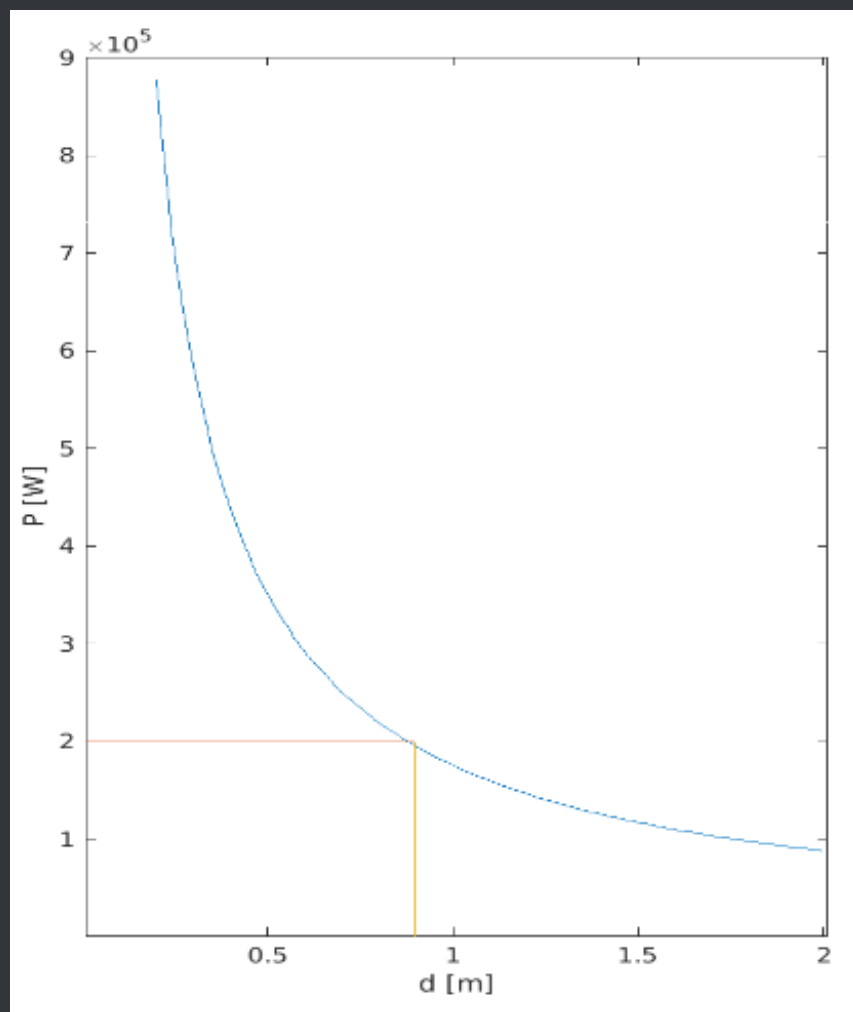
The first dilemma of MiniBee:



	A	X	H	
ROTORS LOCATION	2	5	5	1=DIFFICULT TO CONTROL/LOWER STABILITY
SMALL CONTROL SURFACES	4	2	2	5=EASY TO CONTROL/HIGH STABILITY
SWEEP ANGLE	4	1	4	
WING LOCATION	4	1	2	1=NOT "CLEAN" AERODYNAMICS
ROTORS LOCATION	3	1	1	5="CLEAN" AERODYNAMICS
SWEEP ANGLE	5	2	5	1=HEAVY STRESSED STRUCTURE
ROTORS LOCATION	4	2	2	5=LIGHT STRUCTURE
SUM	26	14	21	

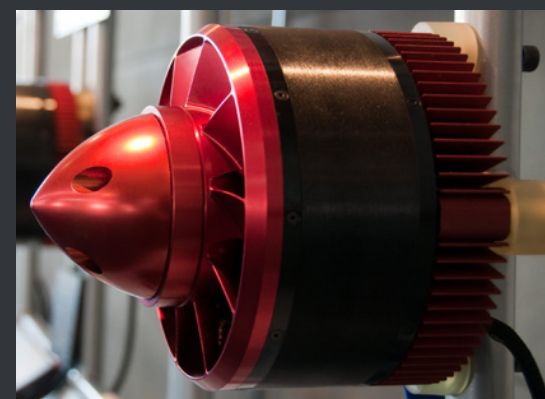
Comparison

Power and diameter estimation



Power: 200 kW
Diameter: 0.9 m

		Yuneec Power Drive 40	Siemens Concept	Emrax 268
Dimensions	Length	163 mm		91 mm
	Width	240 mm		268 mm
	Height	240 mm		268 mm
Weight		19 kg	50 kg	20,3 kg
Power		40 kW at 2400 rpm	260 kW	80 kW at 4000 rpm
Power to weight ratio		2,1 kW/kg	5,2 kW/kg	4 kW/kg



Yuneec Power Drive 40



Emrax 268



Siemens Concept

THERMIC ENGINE

Thermic engine position

- Tractor installation
- Pusher installation

Diesel Engine vs Rotary Engine

Characteristic	SMA SR305-230 ^E		MISTRAL G300	
	Data	N	Data	N
Reliability		2		2
Robustness		2		3
Smooth rotation of the shaft		1		3
No thermic shock cooling		1		3
Low purchase cost	75,000 \$	2	50,000€	3
High power to weight ratio	1.1(=230hp/206Kg) hp/kg	1	1.7(=300hp/177kg) hp/kg	3
Compact size	834*931*784 [mm]	1	632*1145*486 [mm]	3
Simple construction		1		3
Temperature gradient		3		1
Low cost fuel	Diesel 8.06 \$/gallone	3	10LL avgas 12.68 \$/gallone	2
TOT		17		26



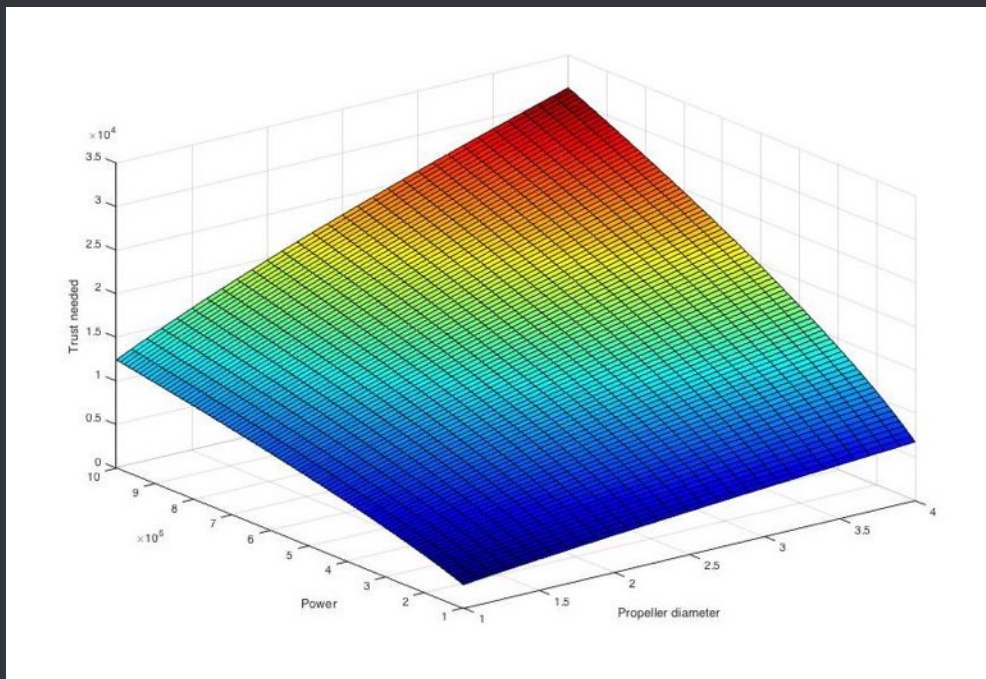
Mistral G300



SMA SR305-230E

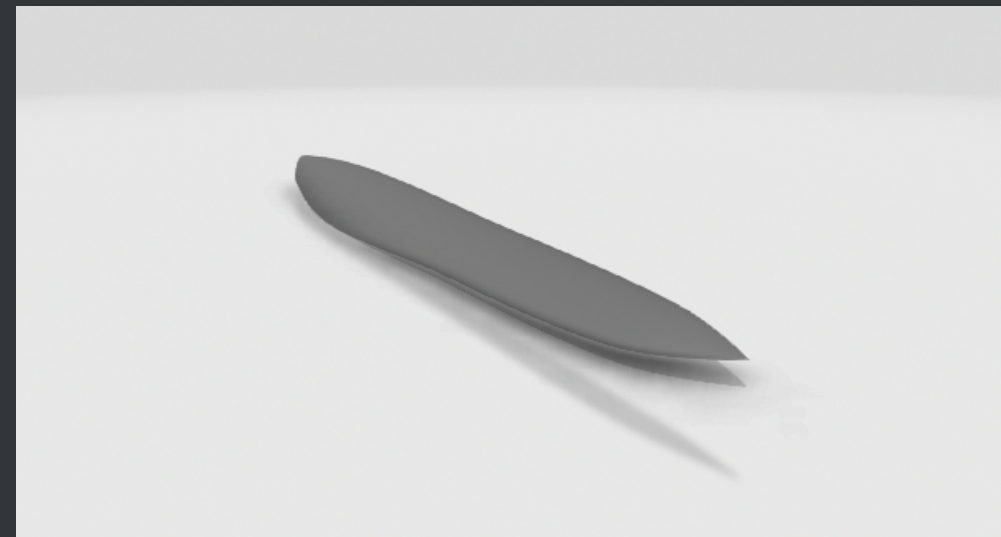
PROPELLER DESIGN

First sizing and DAT



Design

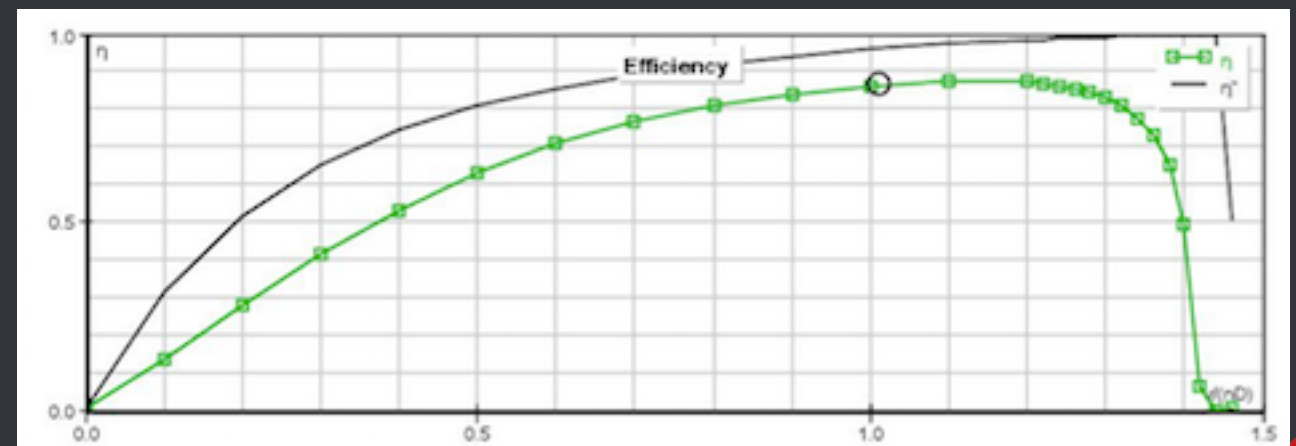
- Blades number: 3
- Flow axial velocity (v): 84 m/s
- Propeller diameter: 2.2 m
- Profiles used for blades
- Available Power: 220 kW
- Air Density: 1.22 kg/m³



Analysis

Pitch:

- Fixed pitch
- Variable pitch on the ground
- Variable pitch



DESIGN OF FUSELAGE

Fuselage is a very important part during the design of an aircraft because it should housing both payload and systems and it is also the structural element who takes together all the aircraft's parts.

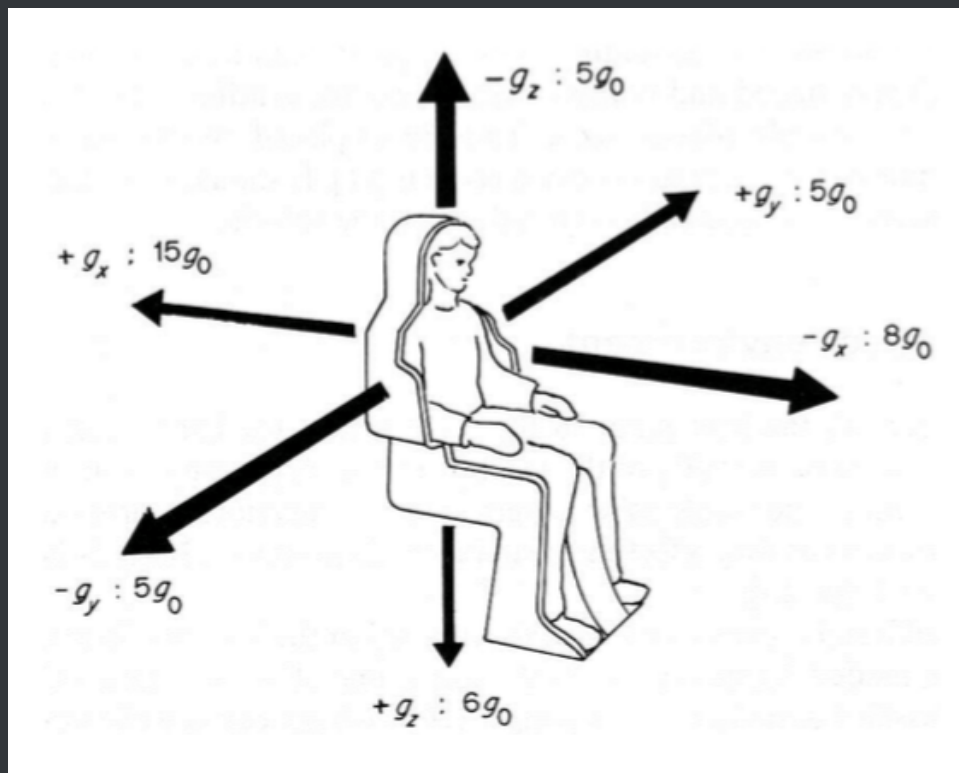
Characteristics	Mark
Pressurization	1
Pilot position and visibility	2
Payload	3
Aerodynamic	3
Access door	2
Engine position	1
Boarding system	2
Wings and electric propeller position	1
Structure	2
Vertical and horizontal tail	2
Low cost	1

DESIGN OF FUSELAGE

Pressurization:

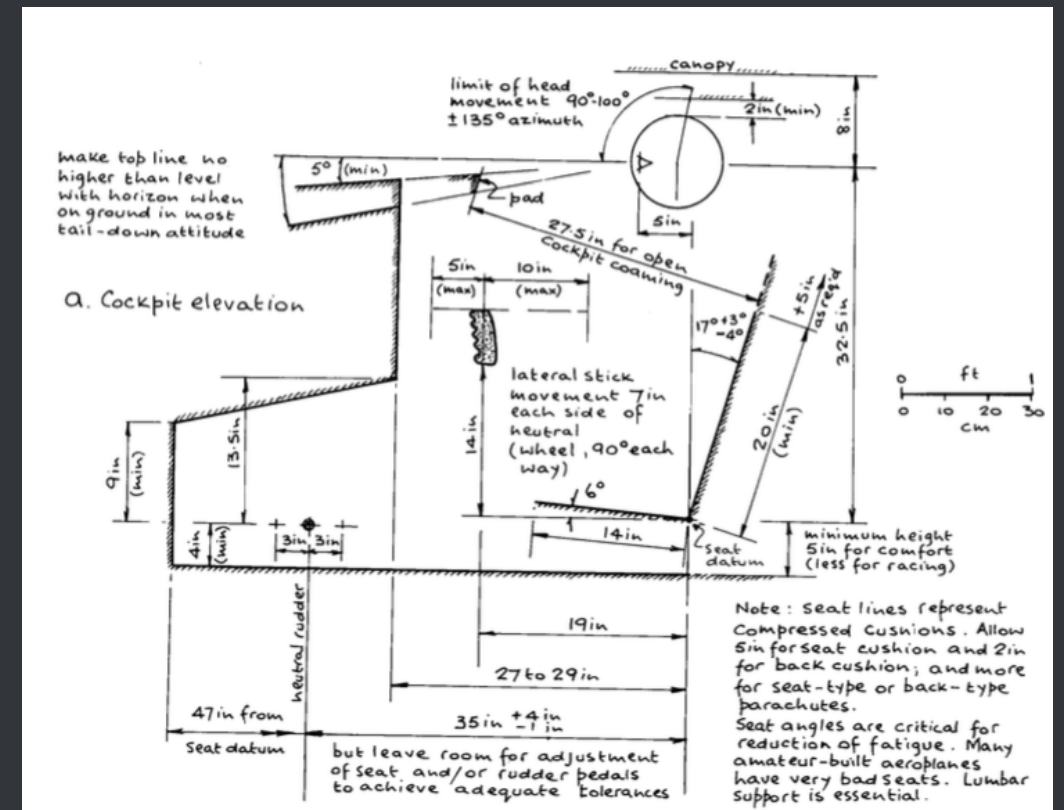
- Low differential pressure
- Normal (high) differential pressure
- No pressurisation

Payload



Boarding system

Pilot position and visibility



Access door:

- wings and rotors presence
- possibility of transport of patients

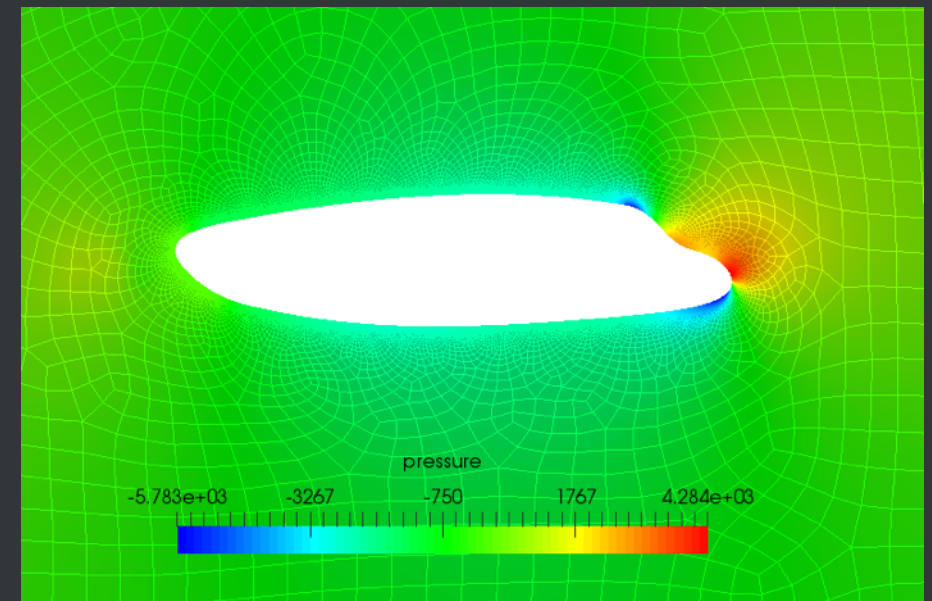
Back door

DESIGN OF FUSELAGE

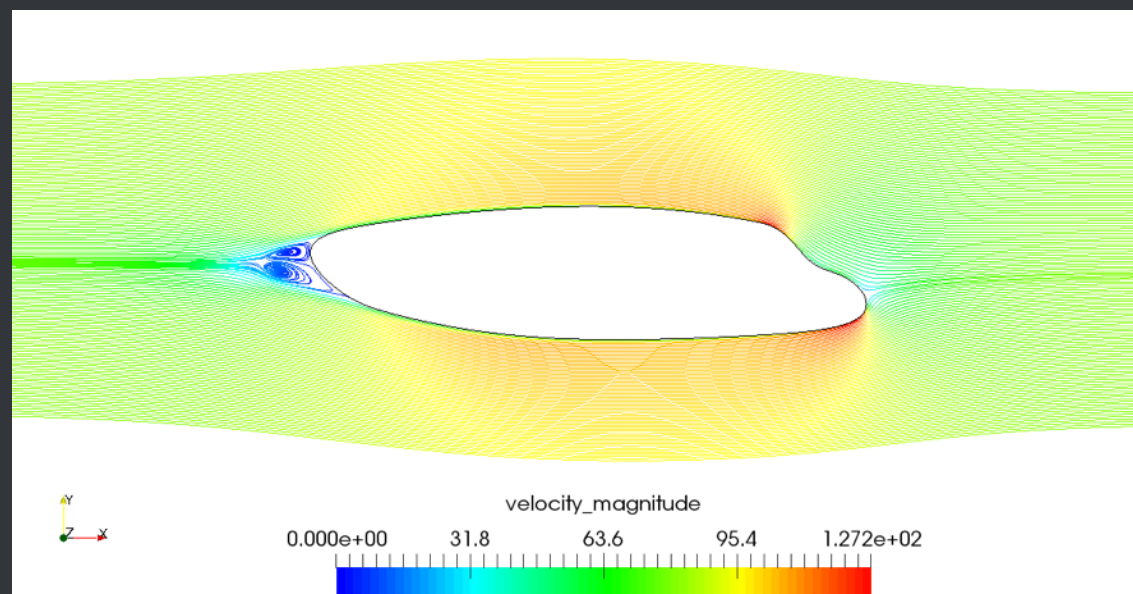
Aerodynamic study

It has been decided to carry out a 2D cross-section fuselage CFD analysis. It is possible to note how the profile of the fuselage can be update to reduce Drag.

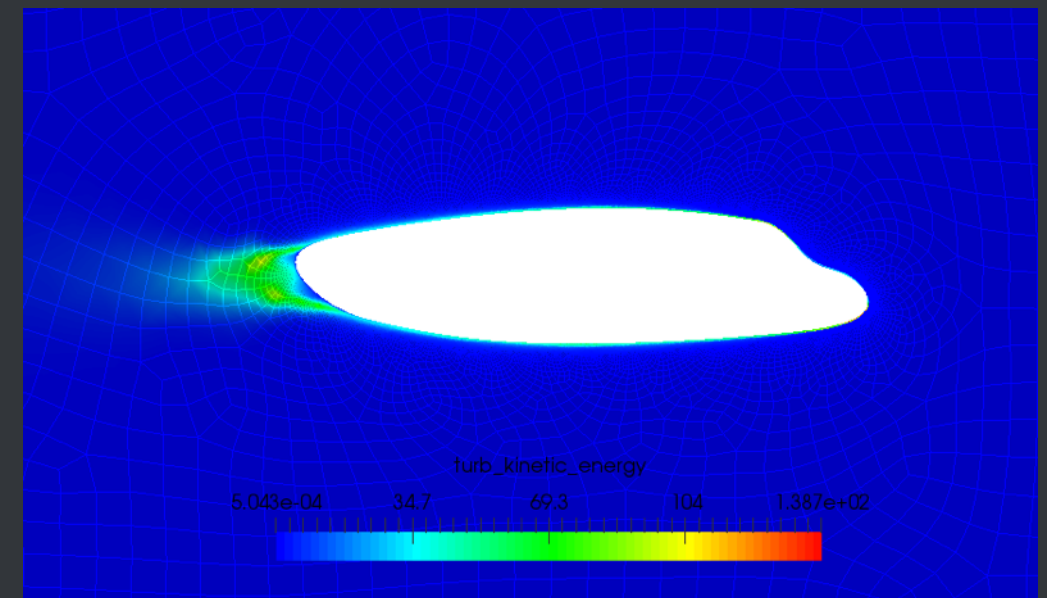
Pressure



Velocity magnitude



Turbulent kinetic energy



DESIGN OF FUSELAGE

Engine position

Tractor configuration

Front position

Vertical and horizontal tail

Single central vertical tail

High horizontal tail

Structure:

Simplicity in construction

Low level of stress

Low cost

Wings and electric propeller position:

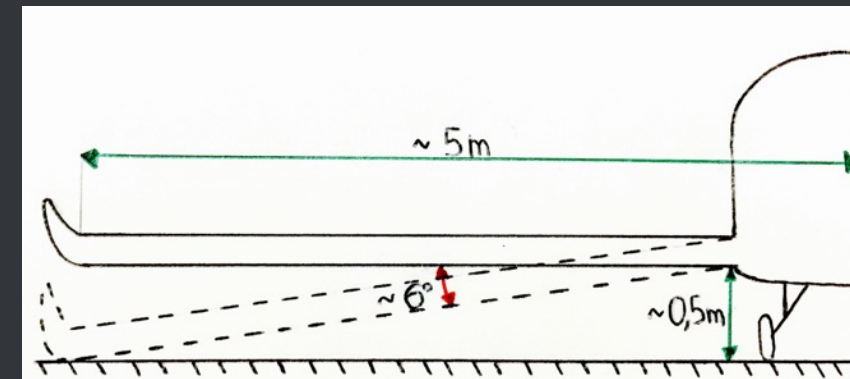
Possible wings position:

-Midi wings

-Low wings

-High wings

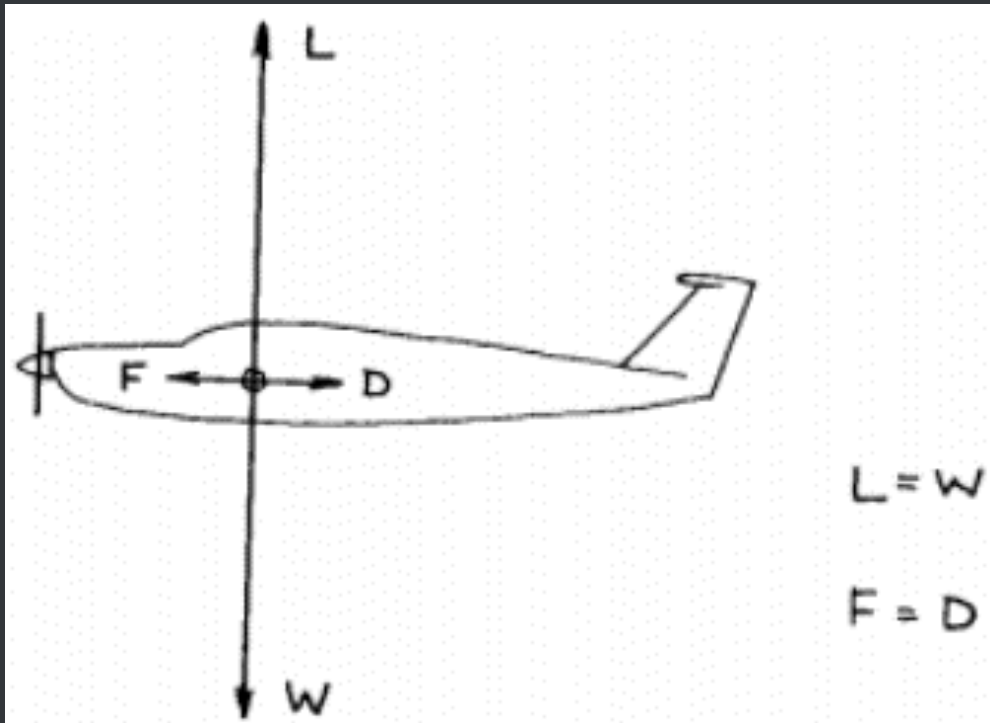
	Mid wing	Low wing	High wing
aerodynamics	3	2	2
stability	2	1	3
structure	1	3	3
visibility	2	1	3
landing inclination	2	1	3
	10	8	14



Electric propeller position:

Medium Height

WING DESIGN

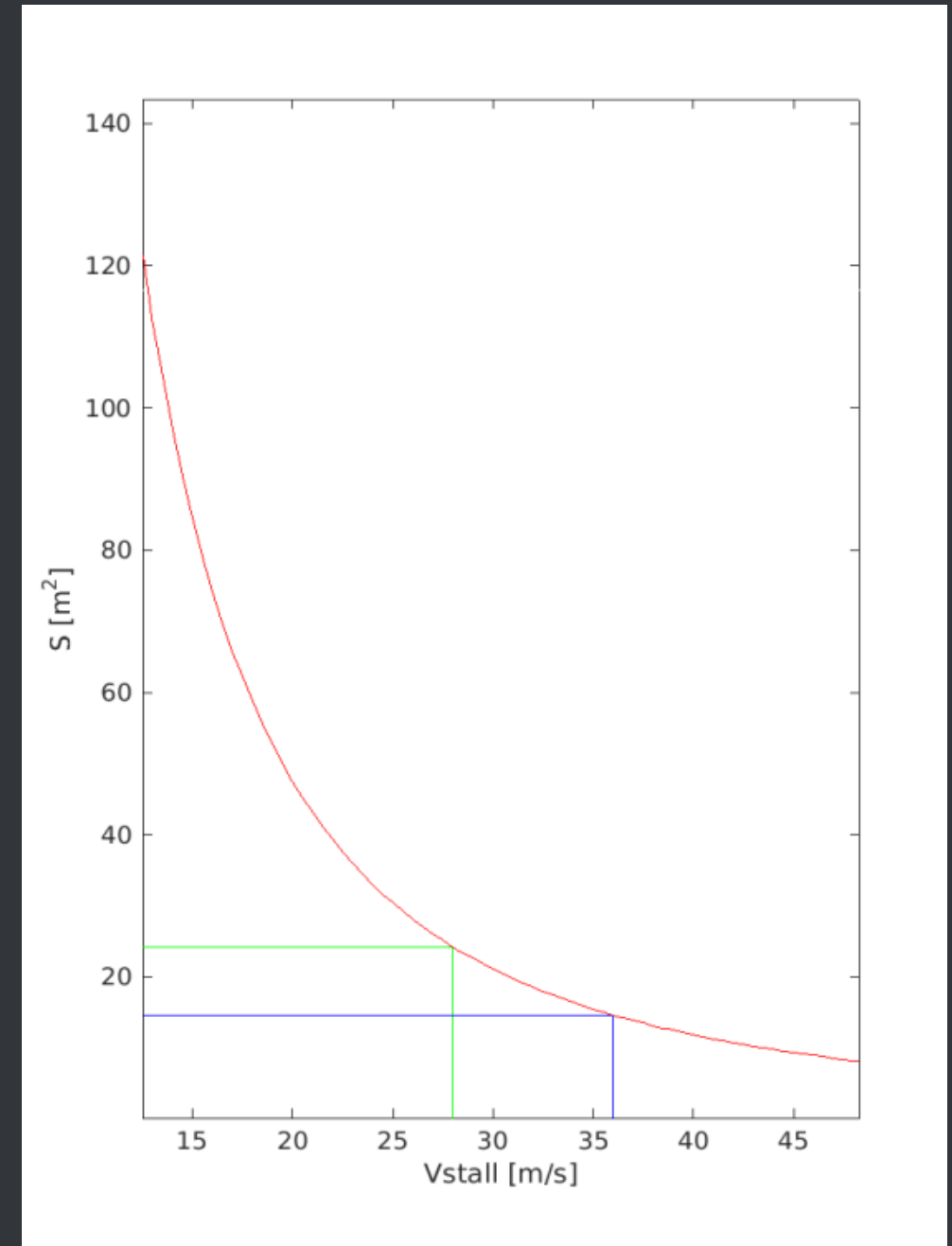


$$L = MTOW = \frac{1}{2} * \rho * V_{stall}^2 * Cl_{max} * S$$

Maximum
Take Off
Weight

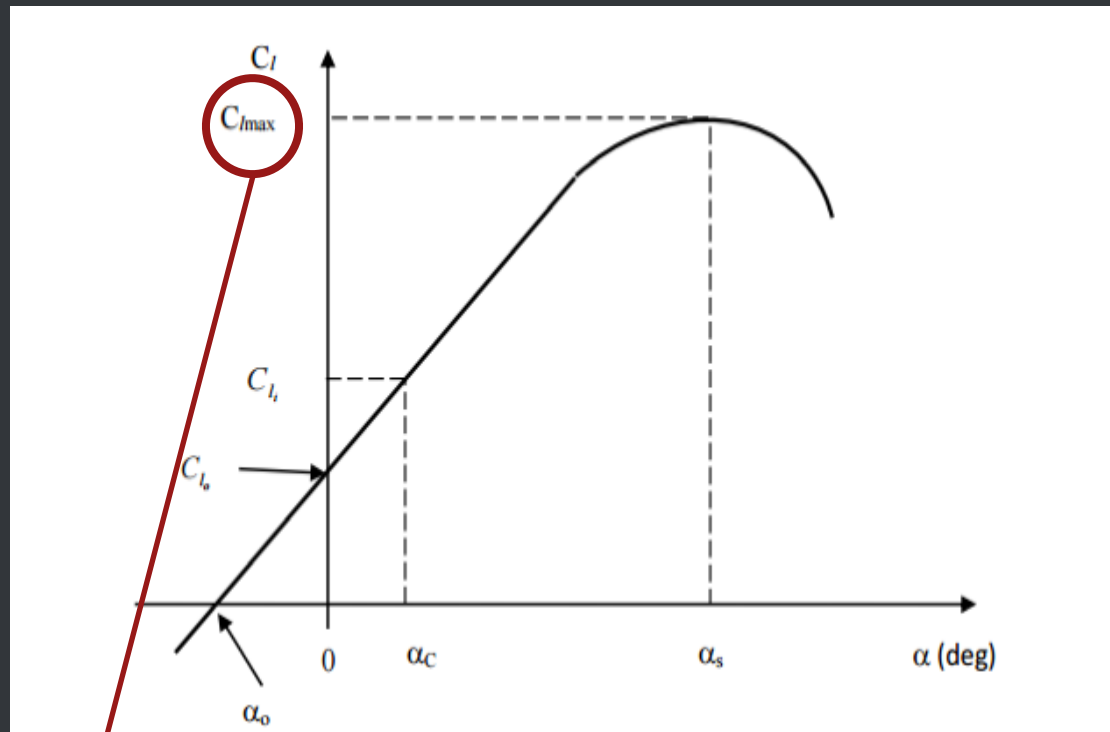
Stall
Speed

Maximum
Cl
coefficient



STALL SPEED = 130 KM/H
WING SURFACE = 18 M2

WING DESIGN



Requirement		NACA 23018	NACA 65 ₂ -415	NACA 64 ₂ -415	NACA 65 ₁ -412
Highest maximum lift coefficient	30%	4	5	5	5
Proper ideal lift coefficient	25%	4	4	4	4
Lower minimum drag coefficient	25%	3	5	4	5
Highest lift-to-drag ratio	10%	2	3	3	4
Lowest C_{mo}	5%	2	3	3	4
Stall quality	5%	2	4	4	3
Proportional sum		3,35	4,4	4,15	4,5

Highest maximum lift coefficient

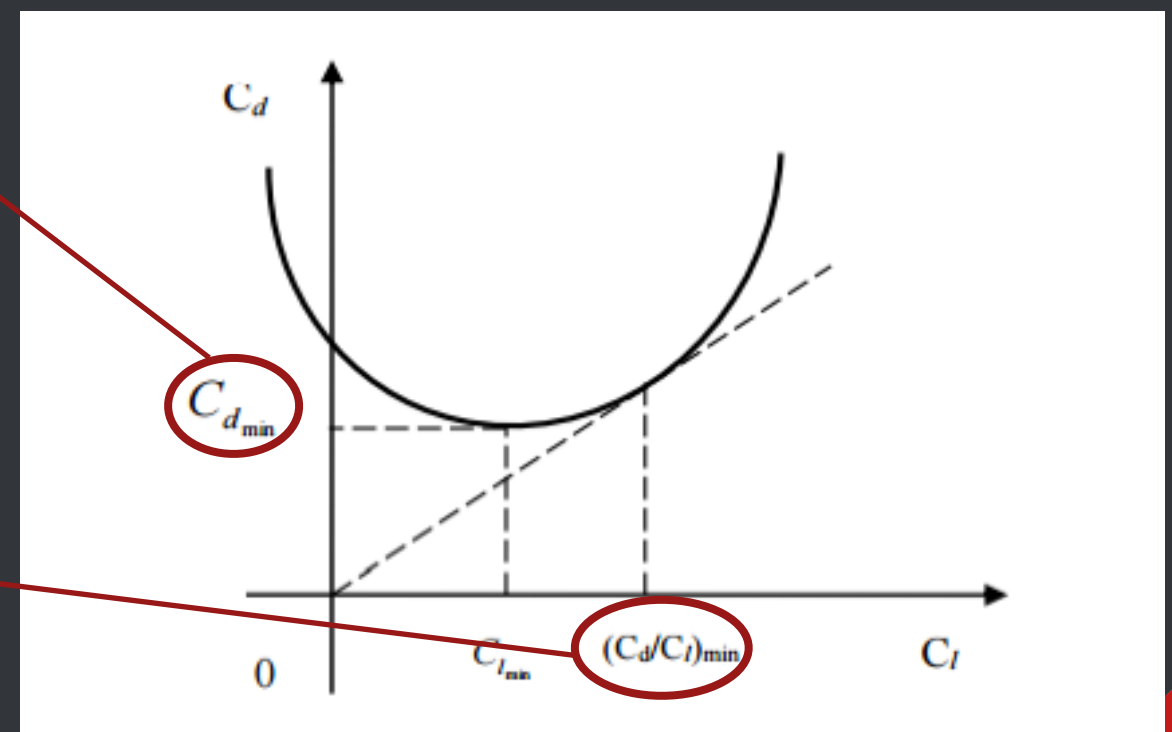
Lower flightcost and the higher maximum cruise speed

Minimum drag coefficient

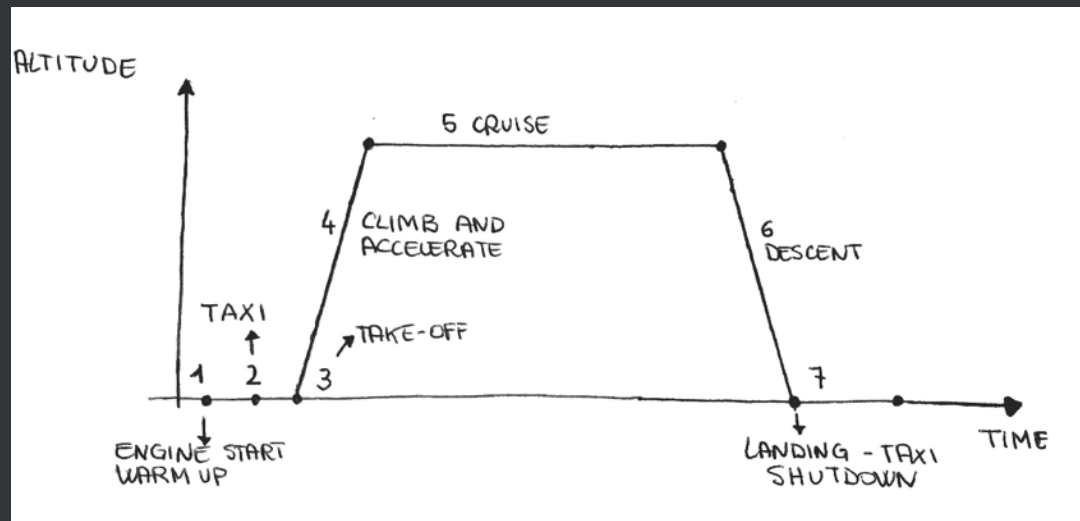
Lowest stall speed

Highest endurance

Highest lift-to-drag ratio



WEIGHT ESTIMATION

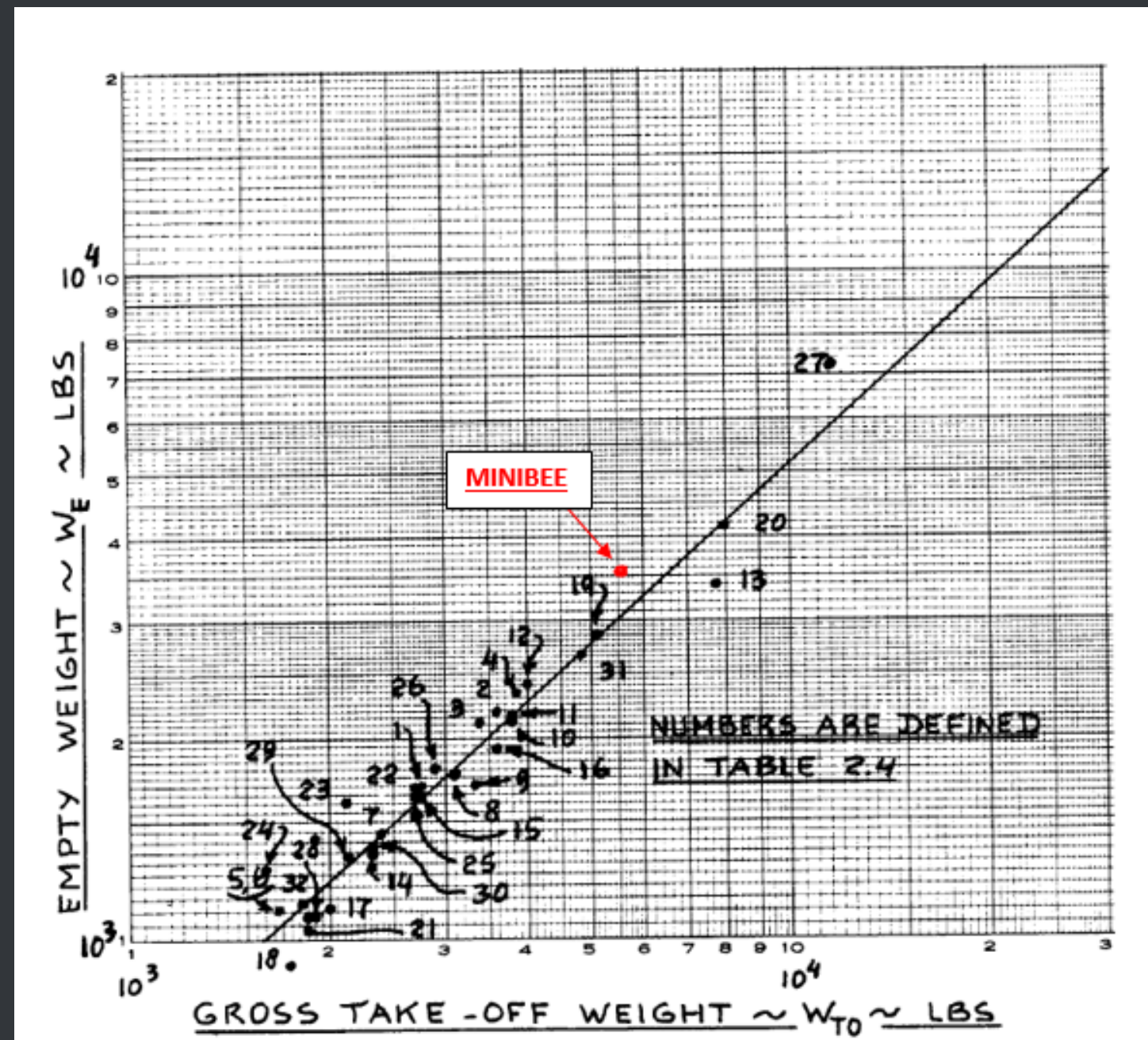


$$MTOW = W_{oe} + W_f + W_{pl}$$

Fuel
Weight

Operating
empty weight
1665 kg

Payload
Weight



WEIGHT ESTIMATION



CESSNA 210 J



CESSNA 310



BEECHCRAFT 95



CESSNA 182

Components
sizing and
locating

CFD
structural
analysis

Weight
model
fraction

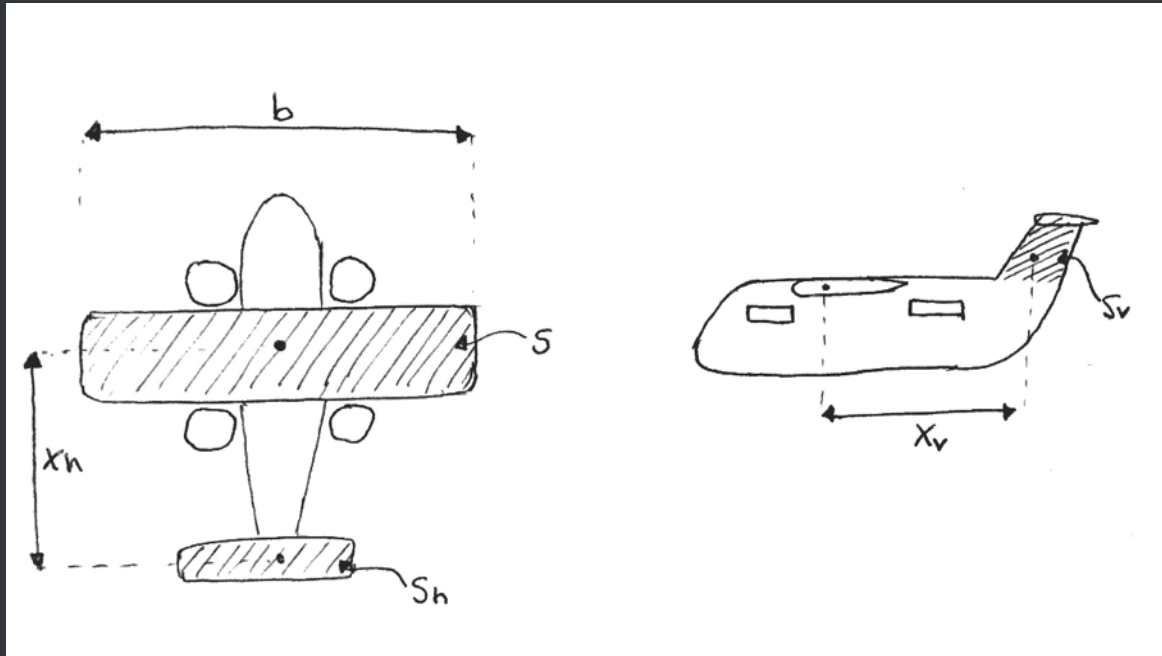
C.G.
locating

Static
margin

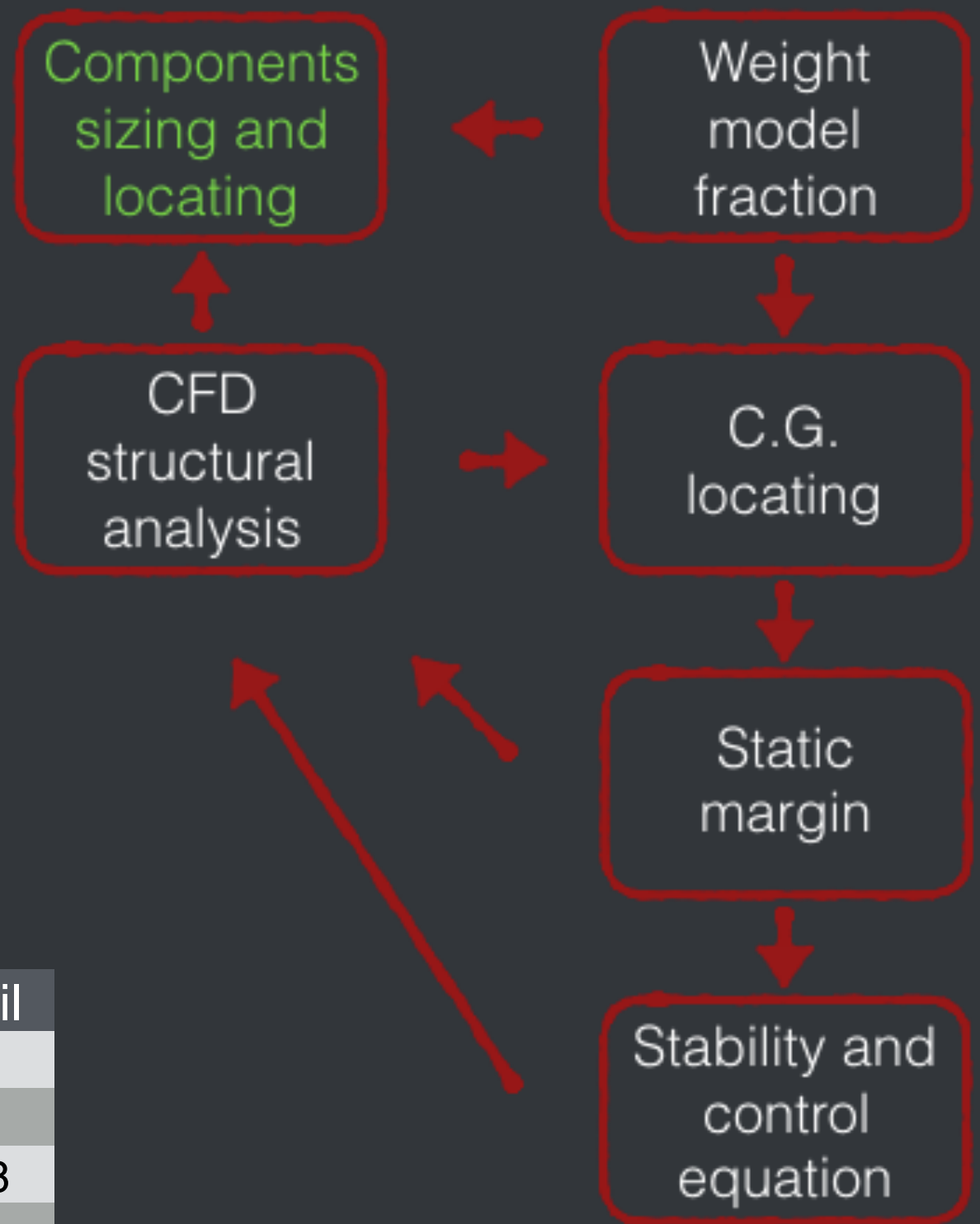
Stability and
control
equation

	AVERAGE Weigh		Adjustment due to		Adjustment due to	
MTOW [KG]			round-off errors		hybrid nature	
EMPTY WEIGHT/ WTO	0,609	1566,26	-43,14	1523,12	141,88	1665,00
FUSELAGE/WTO	0,101	251,76	-6,93	244,83	22,81	267,63
WING/WTO	0,099	247,24	-6,81	240,43	22,40	262,82
TAIL/WTO	0,023	58,40	-1,61	56,79	5,29	62,08
POWER PLANT/ WTO	0,213	533,61	-14,70	518,91	48,34	567,25
LAND GEAR/ WTO	0,054	134,36	-3,70	130,66	12,17	142,83
FIX EQUIP/WTO	0,136	340,89	-9,39	331,50	30,88	362,38

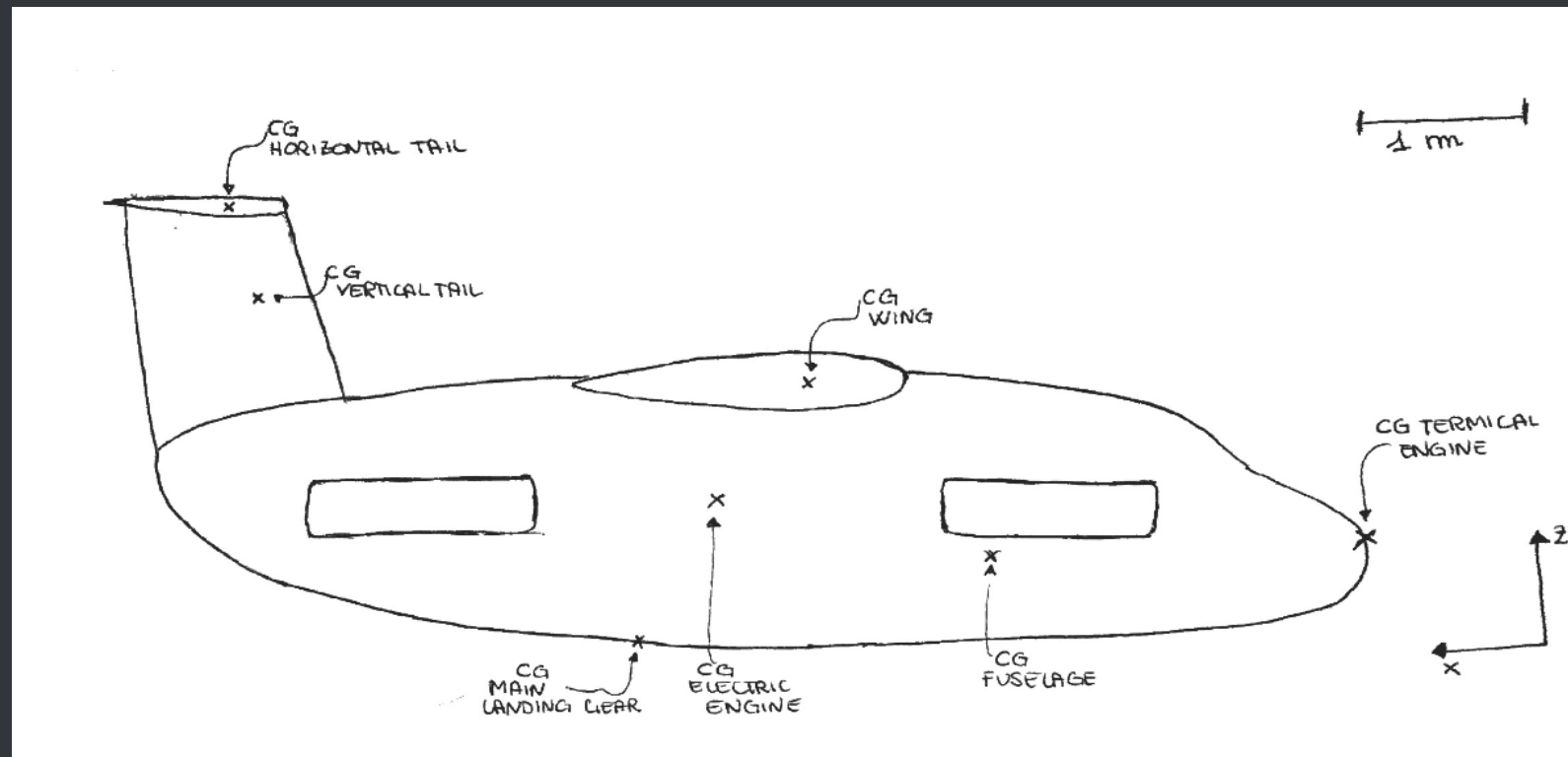
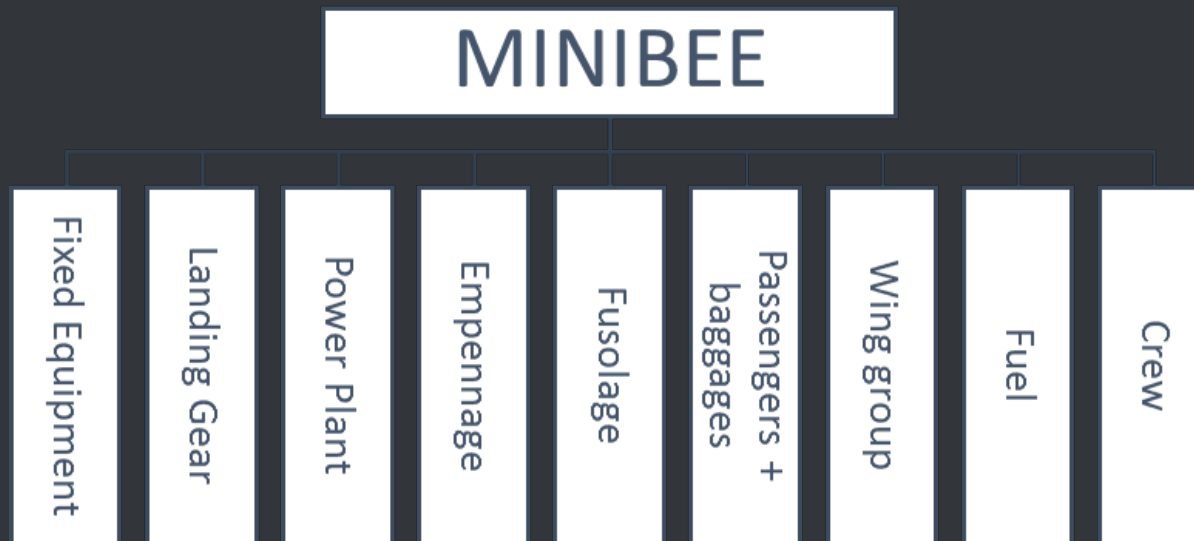
WEIGHT ESTIMATION



	Horizontal tail	Vertical Tail
Sweep angle	7°	30°
Dihedral Angle	0°	90°
Airfoil	NACA 0009	NACA 0018
Incidence Angle	variable	0°
Aspect ratio	5,2	1,7
Volume coefficient	0,8	0,07
S	5 m ²	2 m ²



GRAVITY CENTER



Components
sizing and
locating

CFD
structural
analysis

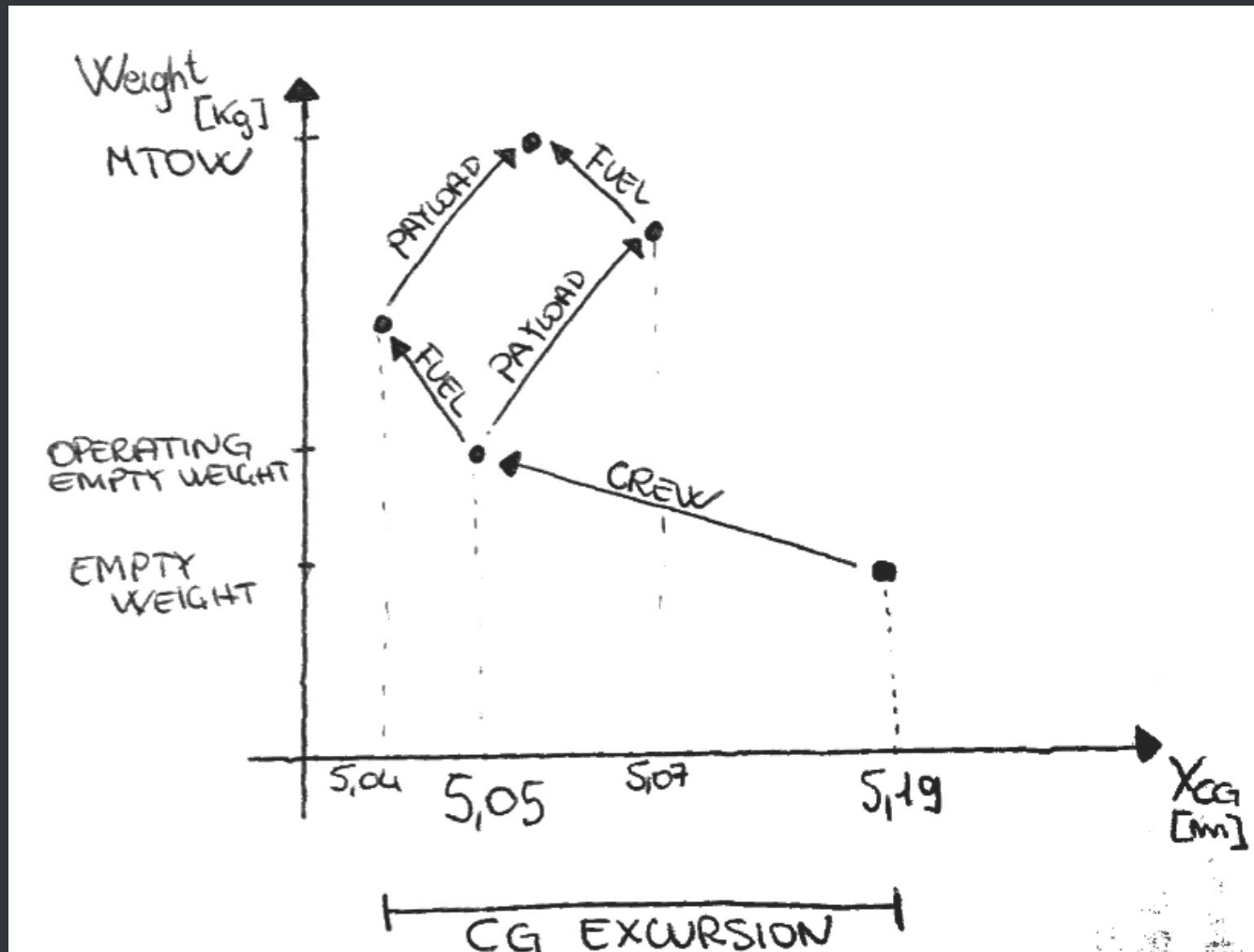
Weight
model
fraction

C.G.
locating

Static
margin

Stability and
control
equation

GRAVITY CENTER



MAXIMUM CENTRE OF
GRAVITY EXCURSION = 0,15m

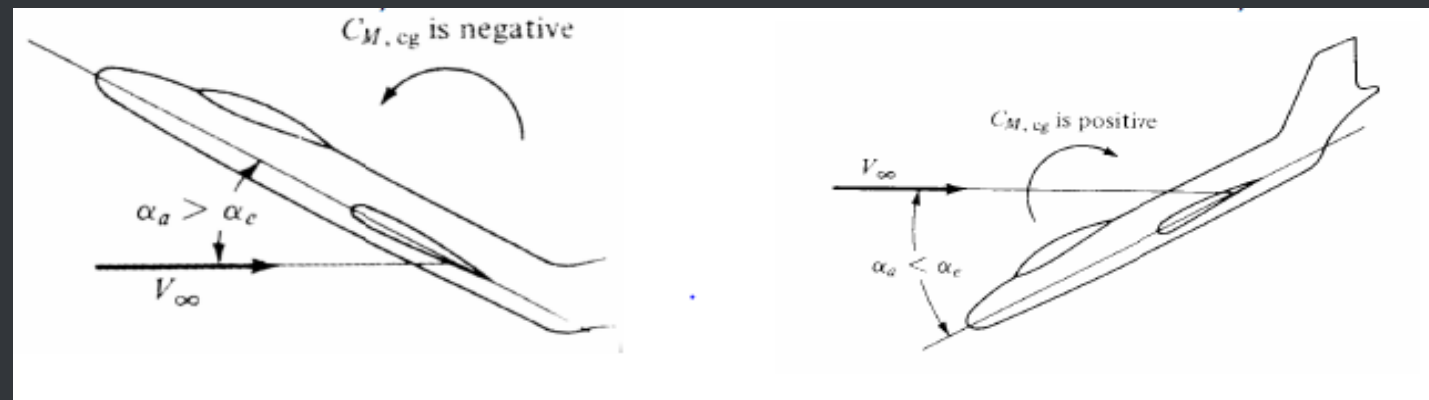
Empty
weight

Empty weight +
crew

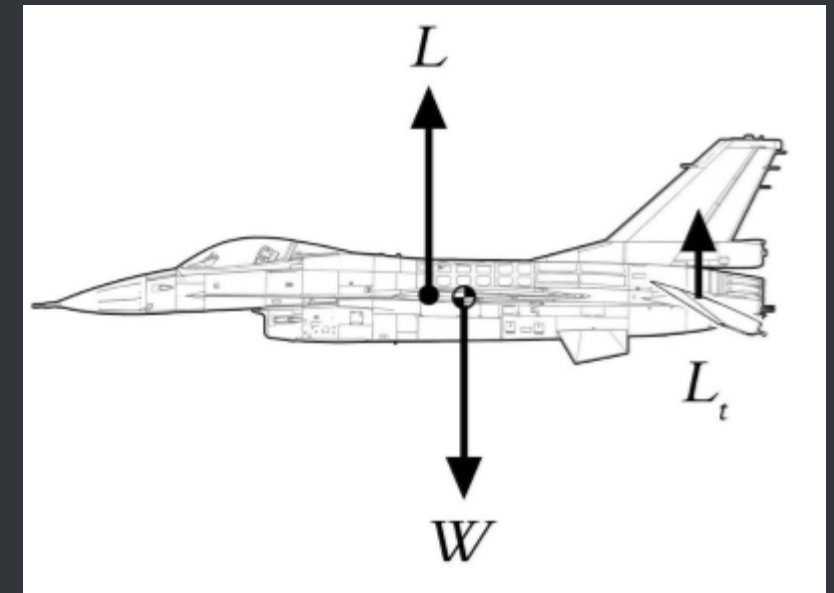
Empty weight +
crew + fuel

Empty weight +
crew + fuel +
payload = MTOW

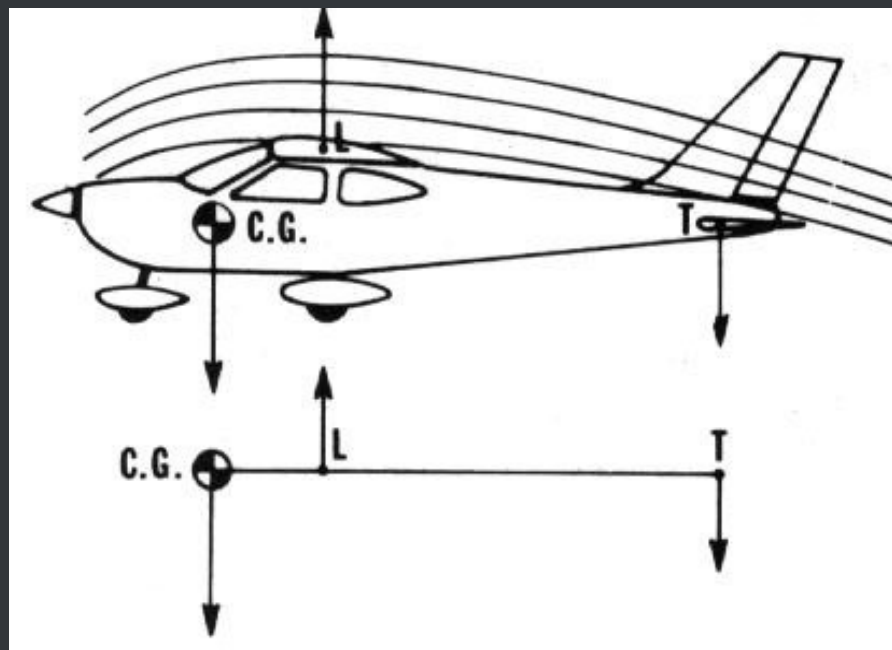
STABILITY



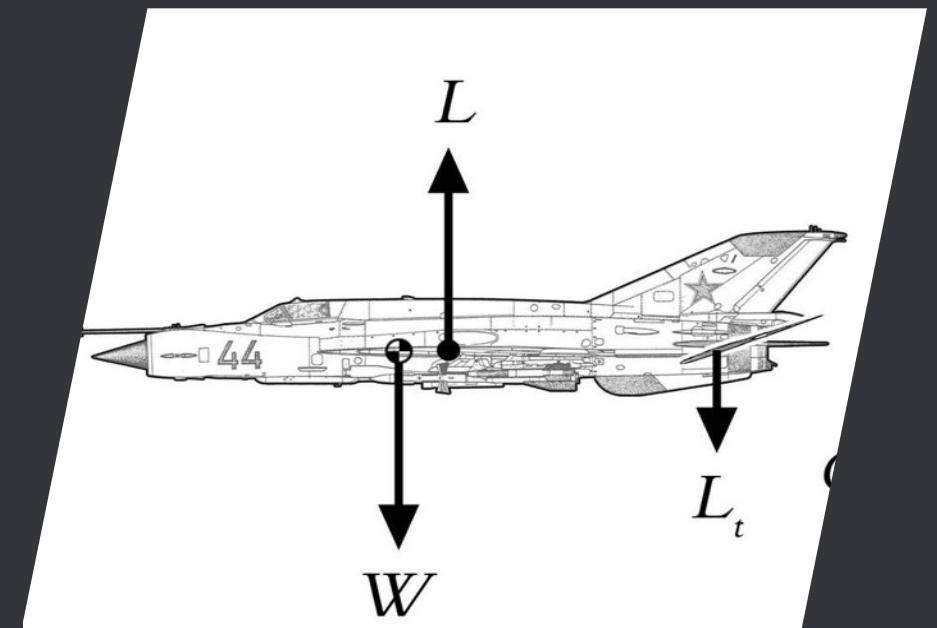
Conventional static stability



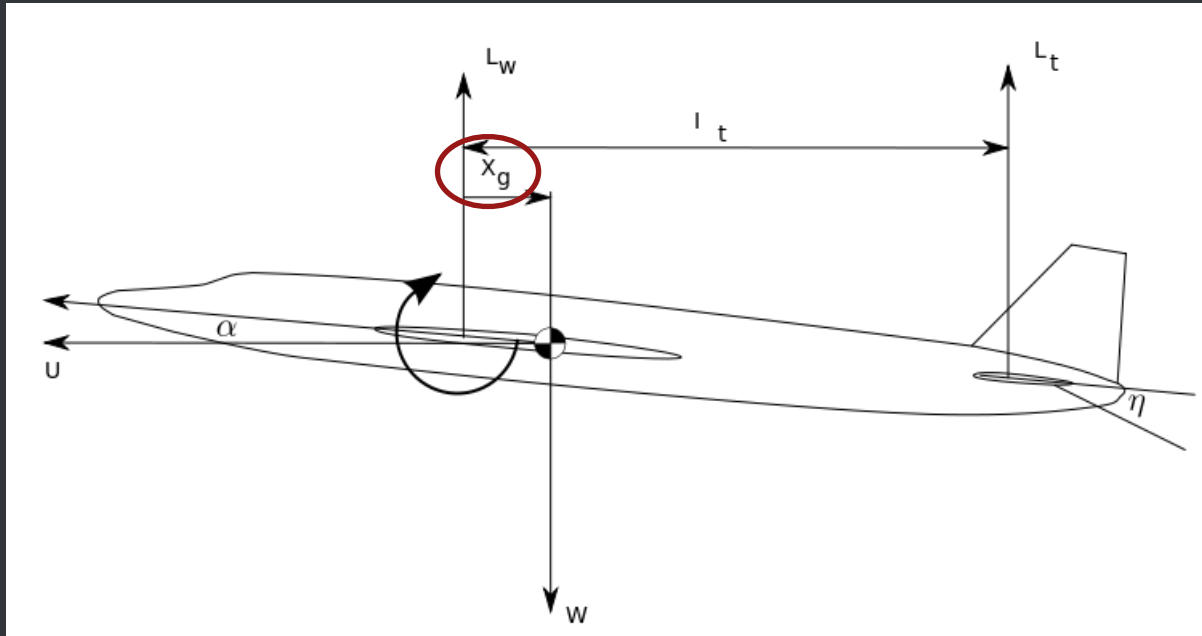
LONGITUDINAL STATIC STABILITY



Relaxed static stability



STABILITY



$$W = L_w + L_t$$

$$M = L_w * x_g - (l_t - x_g) * L_t$$

$$M = h * (L_t + L_w)$$

STATIC MARGIN

$$\frac{\partial M}{\partial \alpha} < 0$$

$$h < 0$$

$$x_g < 0.66 \text{ m}$$

Components
sizing and
locating

Weight
model
fraction

CFD
structural
analysis

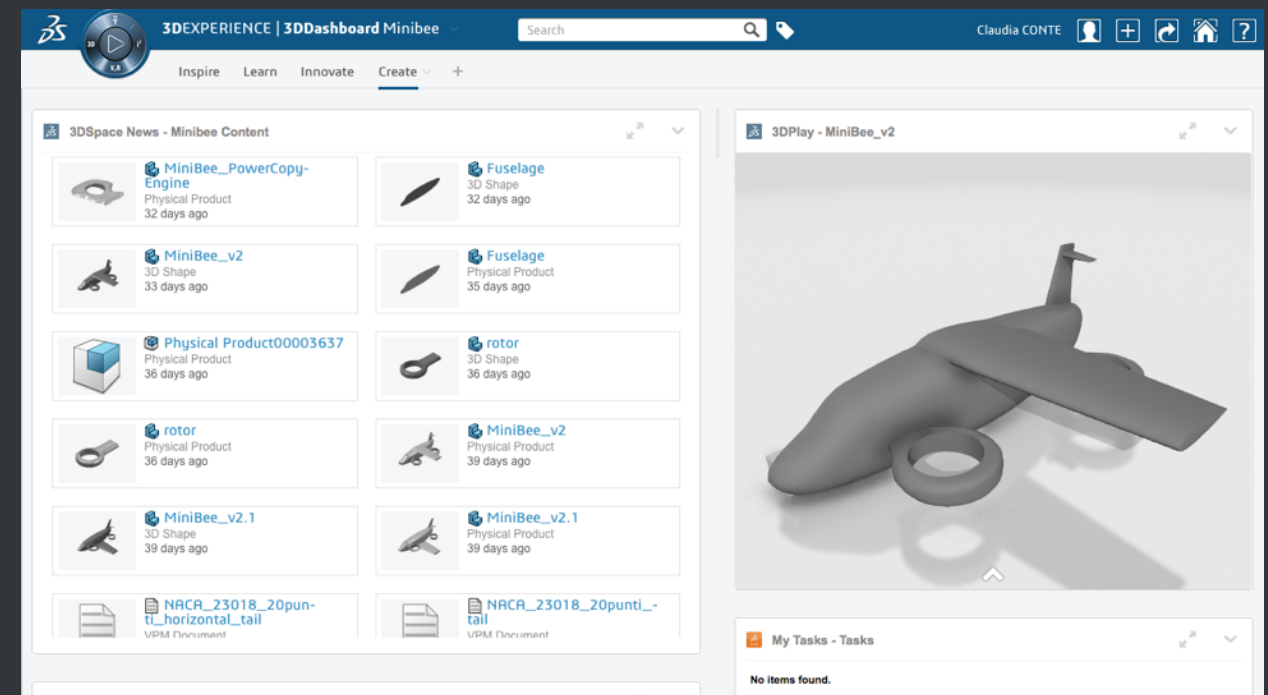
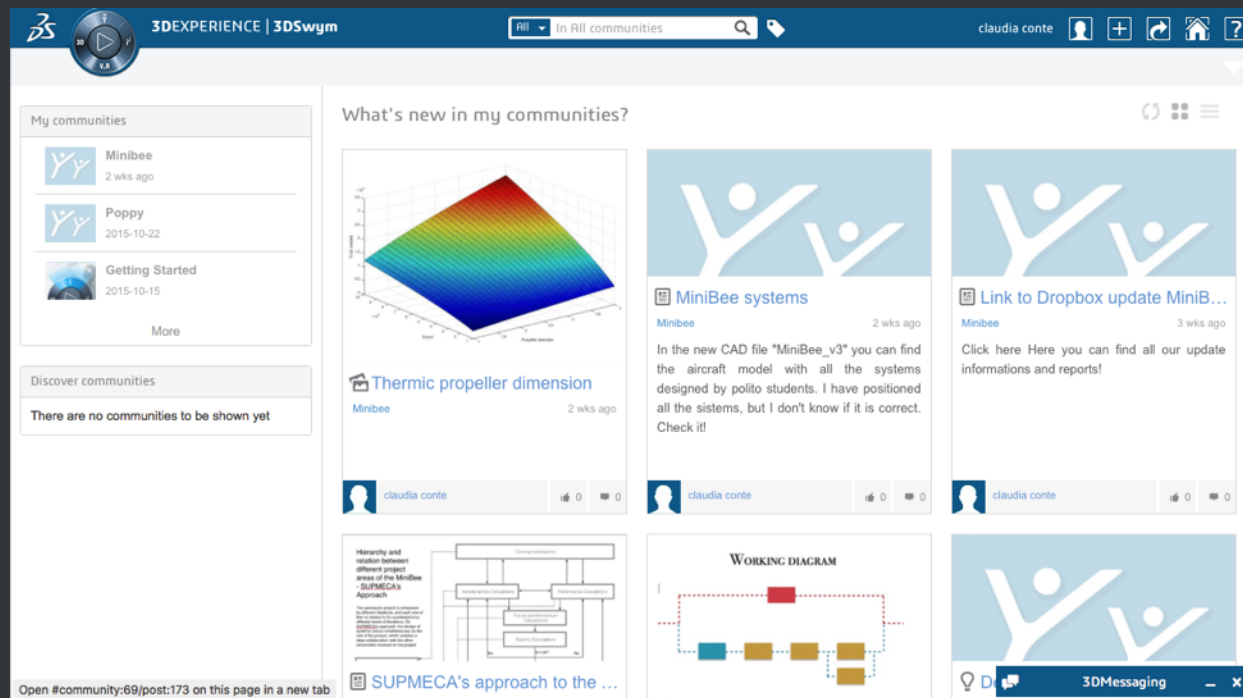
C.G.
locating

Static
margin

Stability and
control
equation

PARAMETRIC CAD

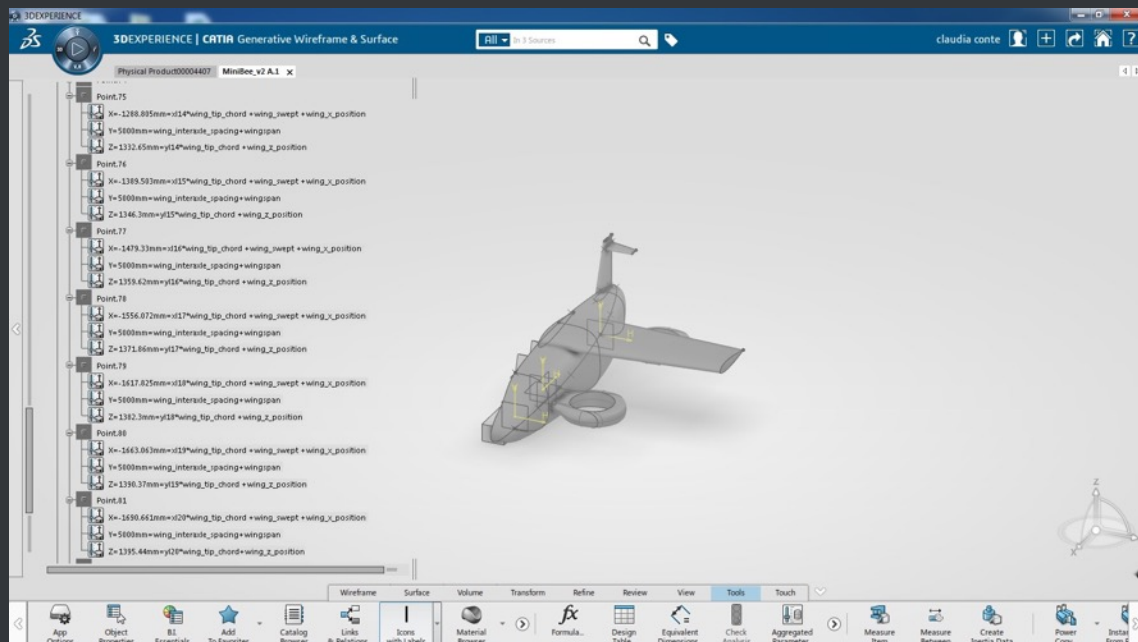
Introduction of 3Dexperience Advantages vs Disadvantages



What is a parametric CAD:

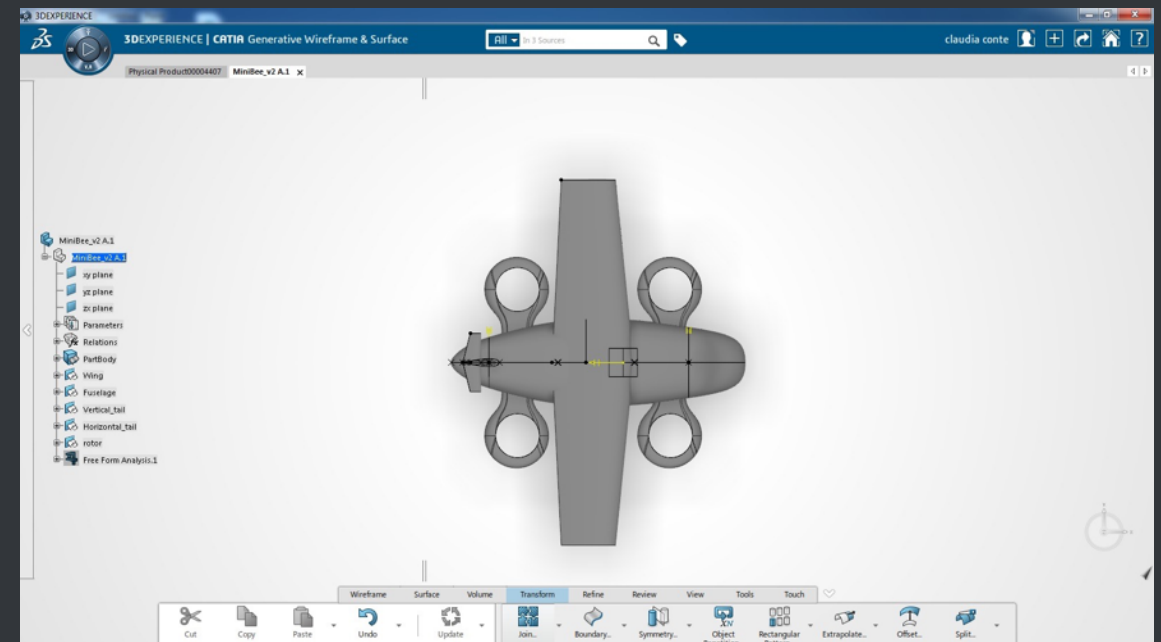
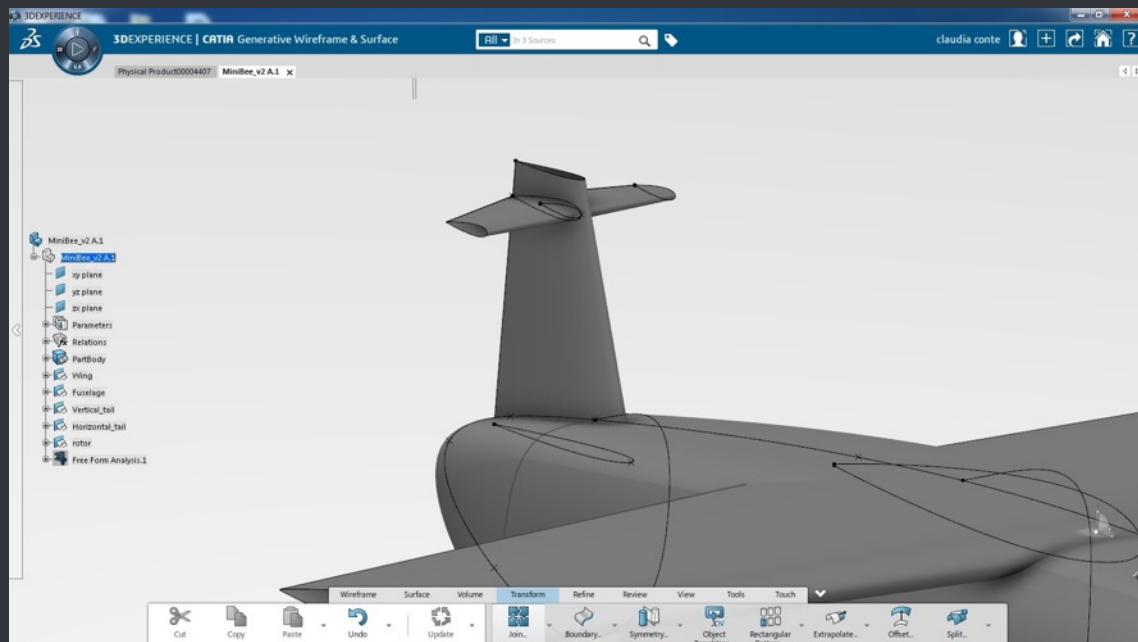
- parameters
- formules
- external link

PARAMETRIC CAD

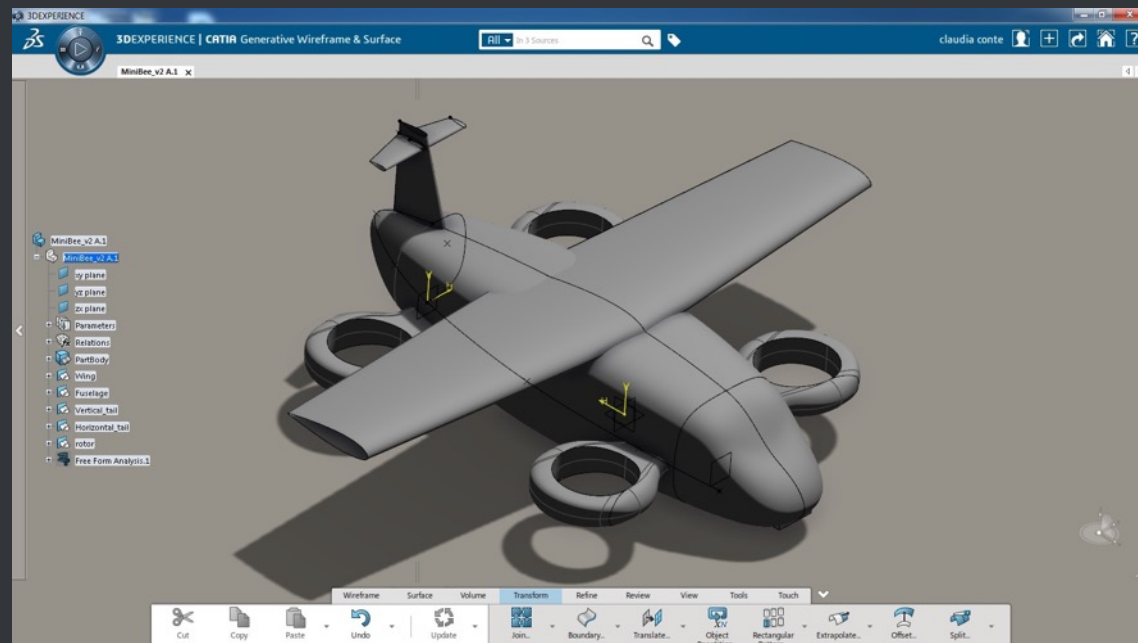


MiniBee specific use:

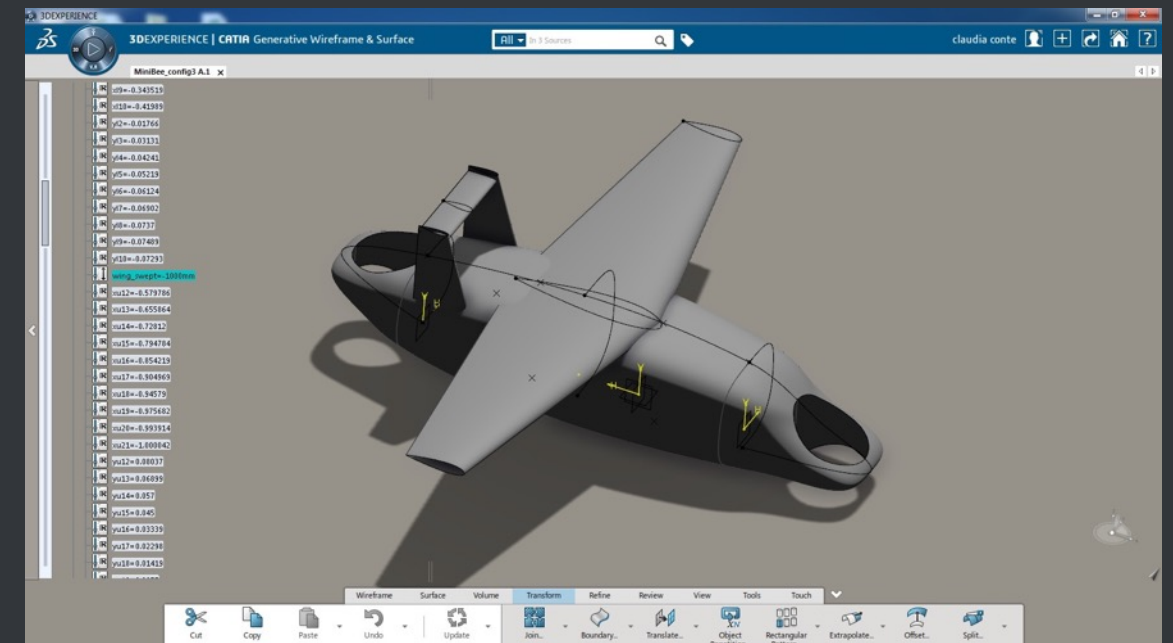
- Link to external excel table
- Design points through formulas
- Additional parameters
- Surface constrains
- Vertical and Horizontal tail definition
- Electric rotors definition



The power of parametric CAD



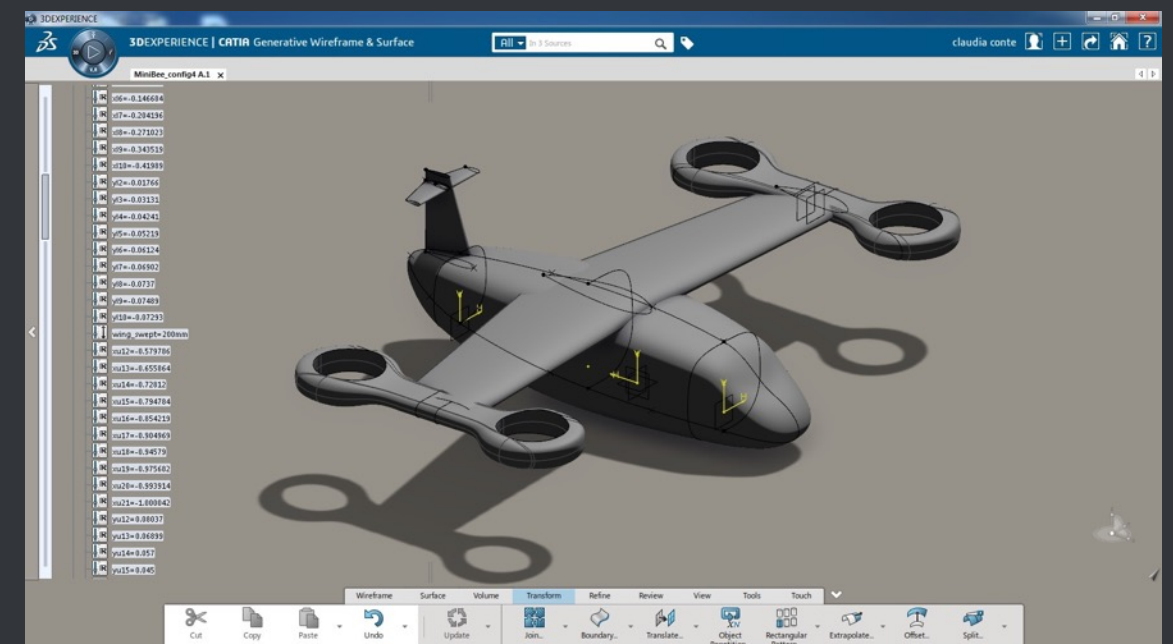
Configuration 1



Configuration 3



Configuration 2



Configuration 4